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MADE EASY
ELECTRONICS ENGINEERING
Analog Electronics
By-Ifteqar Ahamad Sir

- Theory
- Explanation
- Derivation
- Example
- Shortcuts
- Previous Years Question With Solution

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* DEFINITION OF ANALOG CIRCUIT:

* A ckt which consists of at least one electronic device as the major components then that ckt will be electronic circuit

- i) Amplifier.
- ii) Rectifier.
- iii) Oscillator.

* ckt's can be of 3 types

- i) Analog ckt (~~input~~ also analog and output also analog)
- ii) Digital ckt (input digital + output also digital)
- iii) Mixed Electronic ckt (A to D Converter, D to A Converter).

* ANALOG ELECTRONIC CKT:

* An Electronic ckt which performs processing of Analog signals or a ckt in which input and output are Analog signals. Such ckt are called Analog electronic ckt.

- i) Amplifier.
- ii) Rectifier; etc

* Real time signals are Analog signals; hence Analog ckt's (usage) ↙ despite of Digital Era why use Analog ckt's.

* Advantages of Analog circuits are:

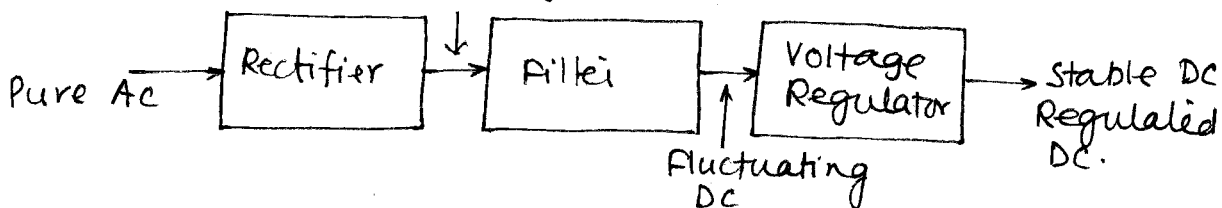
i) Most of the Real time signals are Analog in nature & hence they can be directly processed in Analog circuit. But digital processing requires A to D & D to A Conversion which increases complexity and signal Accuracy is also lost; due to Quantisation Errors.

ii) Analog ckt can process signals having higher power level also. Digital ckt's fails for processing high power supply. Digital ckt's often work in mw range.

* DC POWER SUPPLY: * NOTE: IC's works on DC power supply. They won't work on AC power.

* It converts AC power into DC Power.

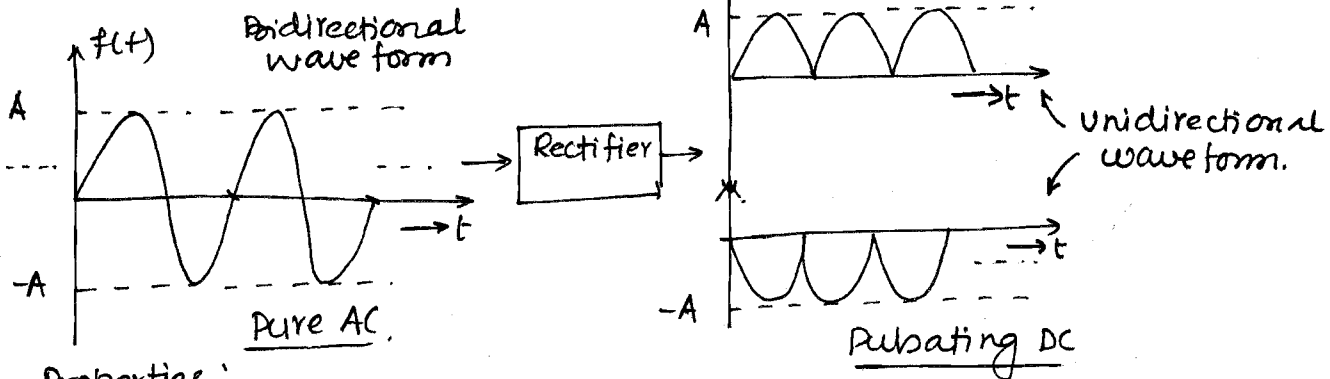
* A Regulated power supply consists of a Rectifier, Filter and a Voltage Regulator



* AC to DC conversion is needed because majority of electronic devices and appliances operate on DC power.

* RECTIFIER CIRCUIT :

* An electronic circuit which converts Pure AC into pulsating DC or a ckt which converts bidirectional waveform into a unidirectional waveform.



Properties :-

- i) Periodic variation
- ii) Bidirectional variation (both in +ve & -ve values)
- iii) Avg. value = 0 (DC value).
- iv) It has single frequency component (sinusoidal).

* Triangular & Square wave are also called as AC signals but not pure AC as they also have harmonics. But AC (Pure AC) should have single freqⁿ component.

Note :-

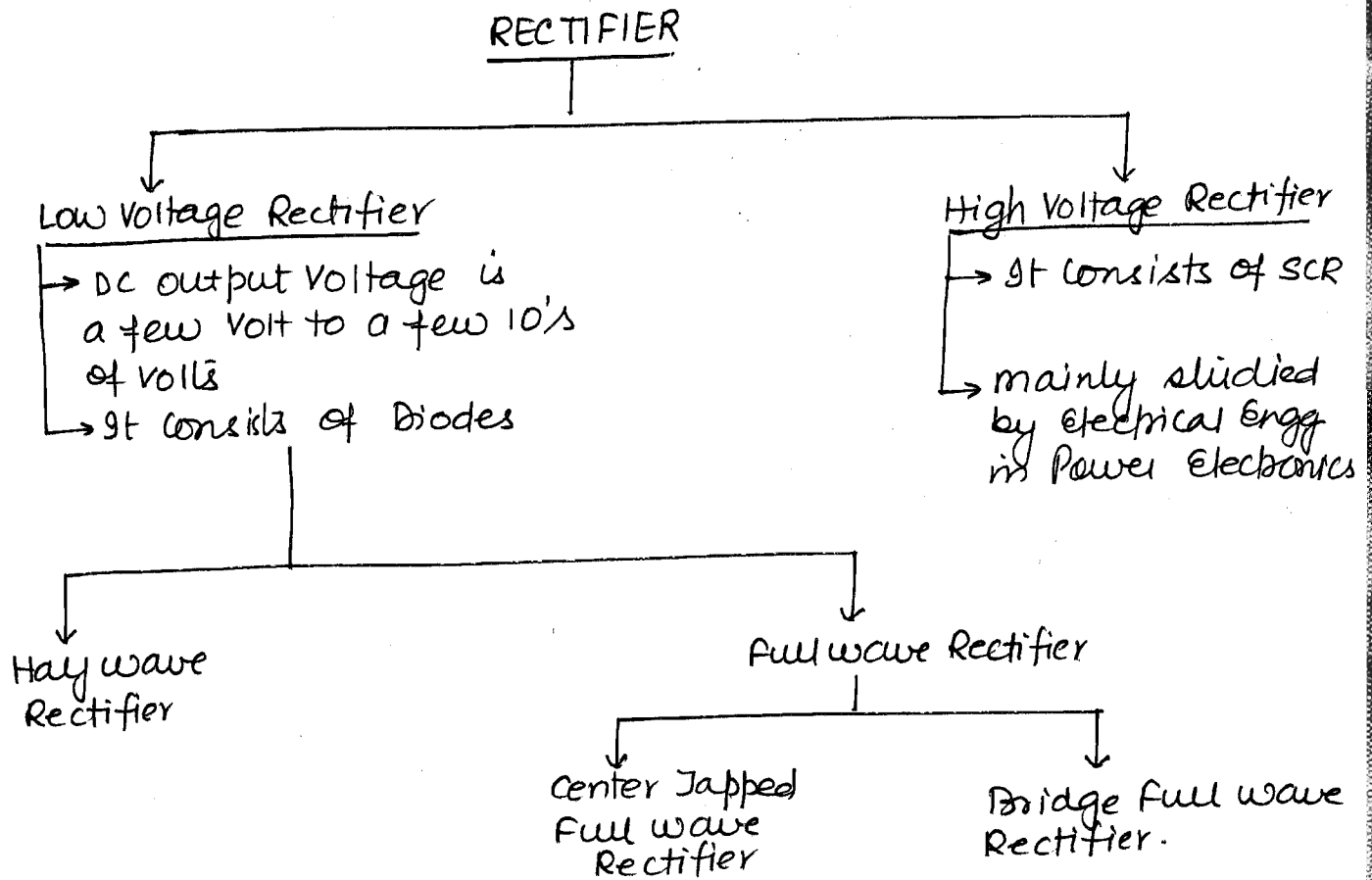
- * Periodic variation indicates presence of AC component that varies with time.
- * Non zero Average indicates presence of DC component
- * Hence Pulsating DC is a combination of AC & DC components.
- * Rectifier converts Pure AC into Pulsating DC.

Properties :-

- i) Periodic variation.
- ii) Unidirectional variation.
- iii) Non zero Avg, hence DC value will be present.
- iv) It has Harmonics.

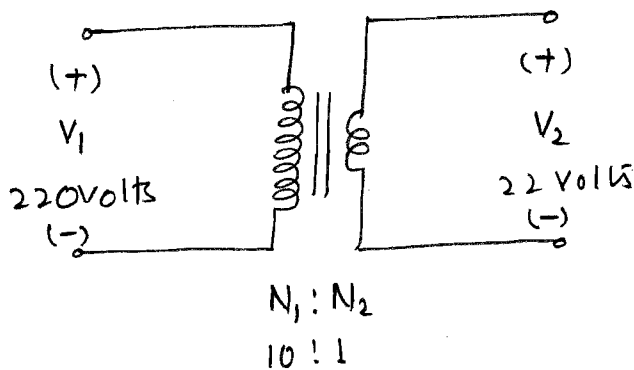
* Time varying signals have AC components.

*Note:



*Note:

* In low voltage Rectifiers, step down Transformer is used to reduce the strength of AC voltage



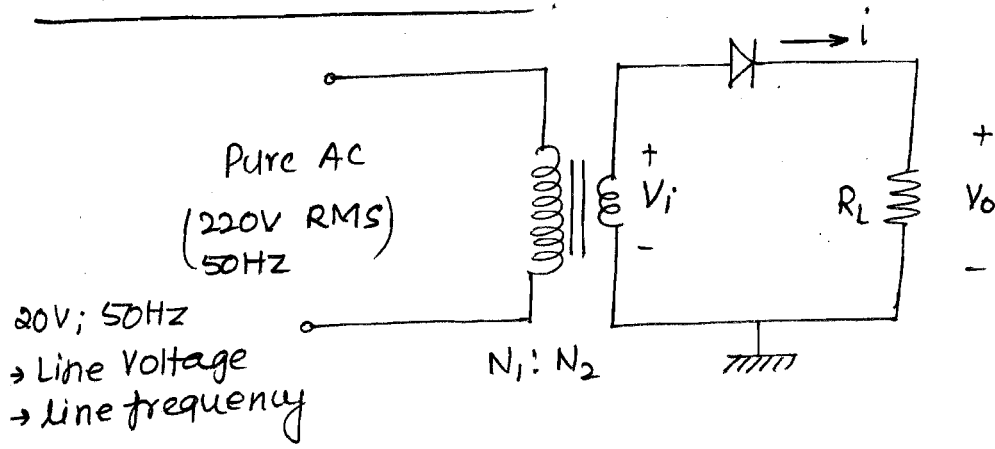
$$\frac{V_1}{V_2} = \frac{N_1}{N_2}$$

* Step down Transformer is needed ∴

i) to get low DC Voltage from Rectifier.

ii) to protect Diodes which have smaller breakdown voltages.

HALF WAVE RECTIFIER:



* V_i : Pure AC Voltage having smaller RMS Value.
 Mathematically,

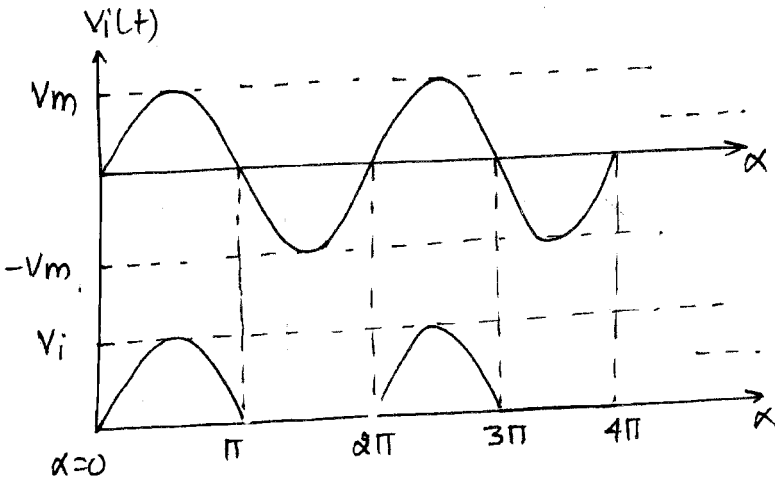
$$V_i(t) = V_m \sin \omega t = V_m \sin \alpha$$

V_m : Peak Value.

$\frac{V_m}{\sqrt{2}}$: RMS Value.

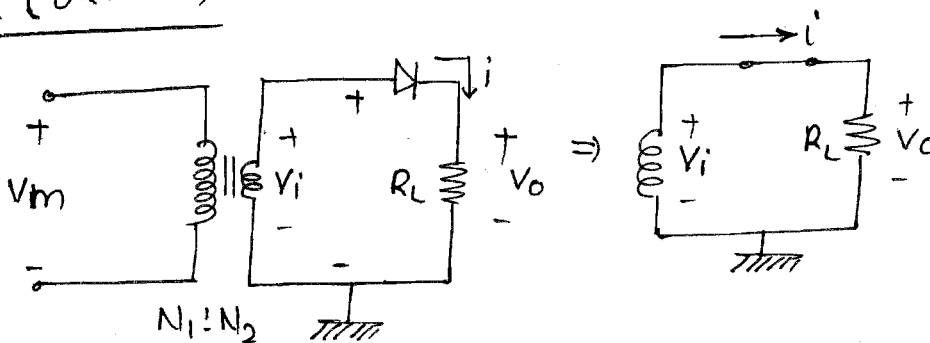
$$314 \text{ rad/sec} = \omega_0 = 2\pi f_0$$

50Hz = f_0 = line frequency ie
 freqⁿ of AC supply
 (50HZ).



Analysis:

CASE I ($0 < \alpha < \pi$) :

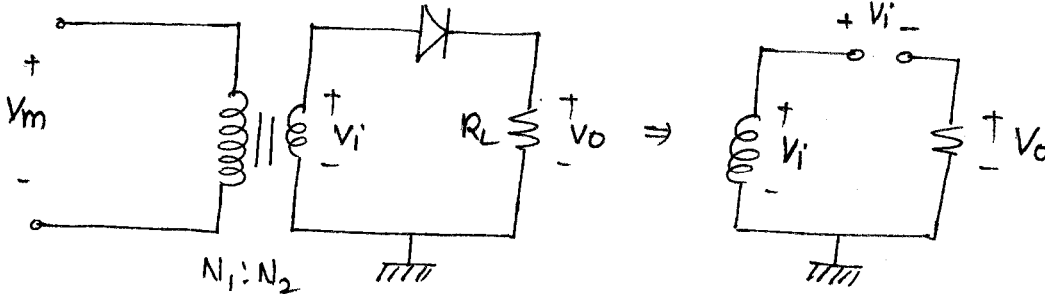


i) V_i is +ve

ii) Diode is in forward Bias \Rightarrow short ckt

iii) $V_0 \approx V_i$

CASE ($\pi < \alpha < 2\pi$) \therefore



* Input voltage appears fully across diode which is acting as open ckt

i) V_i become -ve

ii) Diode is in Reverse Biased \Rightarrow open circuit

iii) $V_0 = 0$

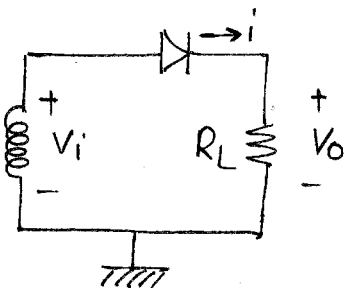
* Analysis of Half wave Rectifier \therefore

i) Instantaneous output current (i) :-

a) $0 < \alpha < \pi$ [Diode is in FB $\equiv R_f$ (few Ω)] :-

R_f = Bulk Resistance of Diode
(Internal Resistance of Diode).

* R_f : Internal Resistance of Diode; we name technically as Bulk Resistance.



* KVL in secondary ckt \therefore

~~$-V_i + i \cdot R_f + i R_L = 0$~~

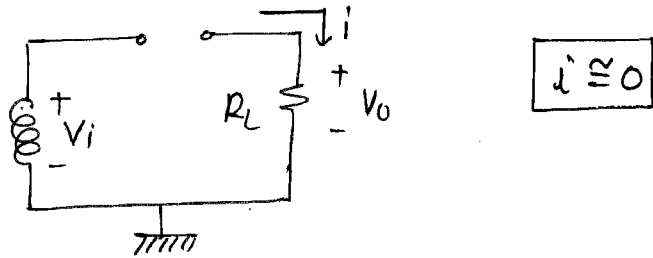
$i = \frac{V_i}{R_f + R_L} = \frac{V_m \sin \alpha}{R_f + R_L}$

$i = I_m \sin \alpha$; $I_m = \frac{V_m}{R_f + R_L}$

1) $\pi < \alpha < 2\pi$ (Diode is in RB) \therefore

* If a diode is in RB, it passes a negligible current equal to Reverse Saturation current.

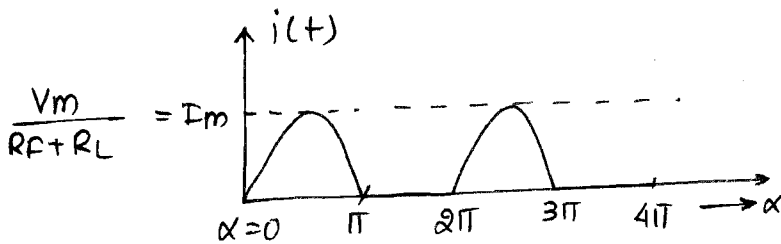
* Reverse Saturation current = nA (Si)
 uA (Ge).



Hence

$$i = I_m \sin \alpha ; 0 < \alpha < \pi$$

$$\approx 0 ; \pi < \alpha < 2\pi$$



*TE

ii) DC output current (I_{DC}) \therefore

I_{DC} = Average value of instantaneous current "i".

Mathematically

$$I_{DC} = \frac{\text{Area}}{\text{Time Period}}$$

$$I_{DC} = \frac{1}{2\pi} \int_0^{2\pi} i \, d\alpha = \frac{1}{2\pi} \int_0^{\pi} I_m \sin \alpha \, d\alpha + 0$$

$$= \frac{I_m}{2\pi} [-\cos \alpha]_0^{\pi} = -\frac{I_m}{2\pi} [-1 - 1]$$

$$I_{DC} = +\frac{I_m}{2\pi} [1 + 1]$$

$$I_{DC} = \frac{I_m}{\pi} A$$

ii) RMS output current (I_{RMS}):

I_{RMS} = RMS value of instantaneous current "i".
Mathematically,

$$I_{RMS} = \sqrt{\frac{1}{2\pi} \int_0^{2\pi} i^2 d\alpha}$$

$$I_{RMS} = \sqrt{\frac{1}{2\pi} \int_0^{\pi} I_m^2 \sin^2 \alpha d\alpha}$$

$$= \sqrt{\frac{1}{2\pi} \times \frac{I_m^2}{2} \left[\int_0^{\pi} d\alpha - \int_0^{\pi} \cos^2 \alpha d\alpha \right]}$$

$$= \sqrt{\frac{I_m^2}{2\pi \times 2} [\pi]}$$

$$= \sqrt{\frac{I_m^2}{4}}$$

$$I_{RMS} = \frac{I_m}{2} A.$$

iv) RMS value of AC component (I'_{RMS}):

* output current of Rectifier is a pulsating DC ie (AC+DC).

$$i = \text{AC Component} + \text{DC Component}$$

$$i = i' + I_{DC}$$

$$i' = i - I_{DC} \leftarrow \text{AC Component.}$$

I'_{RMS} = RMS value of i' .

$$= \sqrt{\frac{1}{2\pi} \int_0^{2\pi} (i')^2 d\alpha}$$

$$(I'_{RMS})^2 = \frac{1}{2\pi} \int_0^{2\pi} (i - I_{DC})^2 d\alpha = \frac{1}{2\pi} \int_0^{2\pi} i^2 d\alpha + \frac{1}{2\pi} \int_0^{2\pi} I_{DC}^2 d\alpha - \frac{1 \times 2}{2\pi} \int_0^{2\pi} I_{DC} i d\alpha$$

$$(I'_{RMS})^2 = \frac{1}{2\pi} \int_0^{2\pi} i^2 d\alpha + \frac{1}{2\pi} \int_0^{2\pi} I_{DC}^2 d\alpha - \frac{2}{2\pi} \int_0^{2\pi} I_{DC} i d\alpha$$

$$= \frac{1}{2\pi} \int_0^{2\pi} i^2 d\alpha + \frac{1}{2\pi} I_{DC}^2 (2\pi) - \frac{2I_{DC}}{2\pi} \int_0^{2\pi} i d\alpha$$

\downarrow I_{RMS} \downarrow I_{DC}

$$(I'_{RMS})^2 = I_{RMS}^2 + I_{DC}^2 - 2I_{DC}^2$$

$$(I'_{RMS}) = \sqrt{I_{RMS}^2 - I_{DC}^2}$$

← An AC Ammeter Connected in series with R_L will record I'_{RMS} . Therefore I'_{RMS} is also known as Reading of AC Ammeter.

Note ∴

* I_{DC} is reading of DC Ammeter.

∴ RIPPLE FACTOR (r) ∴

* The unwanted AC component which is present in the O/P of the Rectifier is known as Ripple.

* Ripple factor is a measure of the amount of AC component

Mathematically,

$$r = \frac{\text{RMS value of AC component}}{\text{DC component}}$$

$$r = \frac{I'_{RMS}}{I_{DC}} = \frac{V'_{RMS}}{V_{DC}}$$

As AC component is unwanted, Ripple factor should be smaller, and ideally should be zero.

* Analysis ∴

$$r = \frac{I'_{RMS}}{I_{DC}} = \frac{\sqrt{I_{RMS}^2 - I_{DC}^2}}{I_{DC}} = \sqrt{\left(\frac{I_{RMS}}{I_{DC}}\right)^2 - 1}$$