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**UNACADEMY
CIVIL ENGINEERING
HYDRAULIC MACHINE
BY-JASPAL SIR**

- Theory
- Explanation
- Derivation
- Example
- Shortcuts
- Previous Years Question With Solution

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HYDRAULIC MACHINE

-JASPAL SINGH
(Ex IES)



• Dynamic action of fluid



- A stream of fluid entering in machine (turbine, pump, motor) has fixed or definite direction.
- A force would be required to be acted on fluid to change its velocity (either in direction or in magnitude).
- The fluid also exert the same amount of force on the machine as is being acting on it (according to Newton's third law of motion).
- Also, this force is exerted by the fluid on the machine or its compon-

ent is by virtue of motion and is termed as "DYNAMIC FORCE" (and must not be confused with the hydrostatic force).

→ Thus, dynamic force on jet of fluid can be computed using momentum equation.

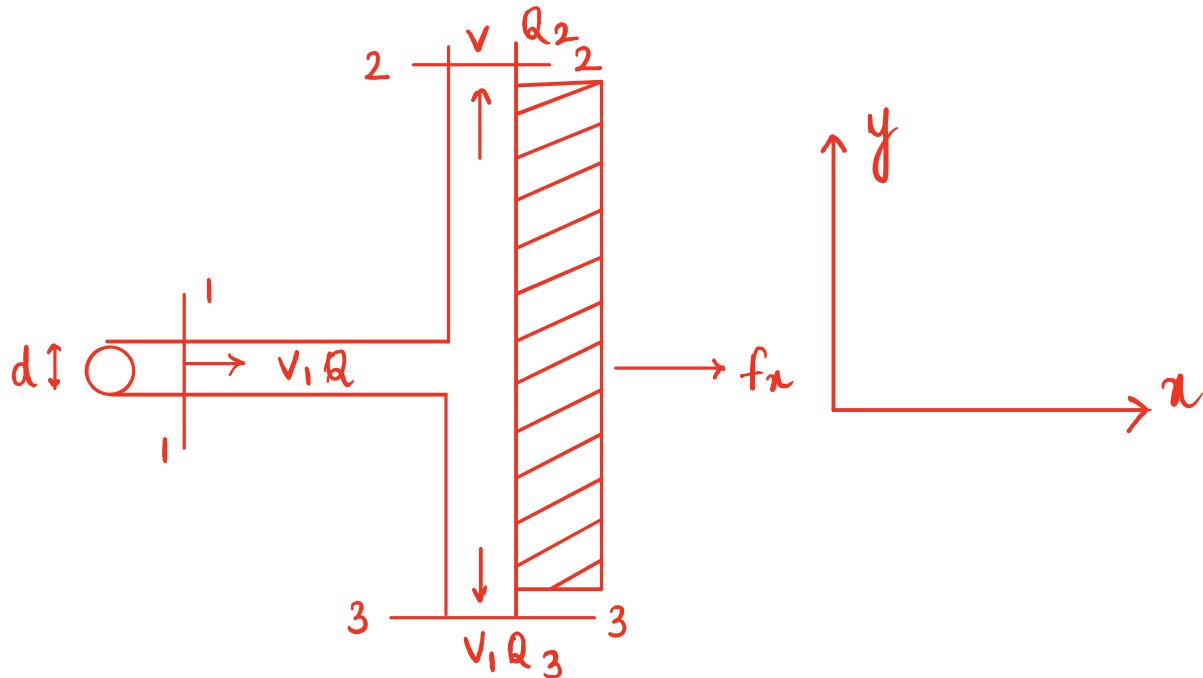
Dynamic force on jet of fluid = rate of
(in given direction) change of
linear momentum of jet
in same direction.

Also force on machine or component =
force on jet of fluid.

I. force Exerted by fluid jet on stationary plate (flat).



a) Plate held normal to the jet.



→ If plate is frictionless, using energy equation between 1-1, 2-2, 3-3.

$$\frac{P_1}{\gamma} + Z_1 + \frac{V_1^2}{2g} = \frac{P_2}{\gamma} + Z_2 + \frac{V_2^2}{2g} + h_2$$

$$= \frac{P_3}{\gamma} + Z_3 + \frac{V_3^2}{2g} + h_3.$$

$$V_1 = V_2 = V_3 = V$$

Now force exerted by jet on the plate =
 - force exerted on jet by plate.

$$f_x = -(pQ(0) - pQV) = pQV.$$

$$= p(AV)V = pAV^2.$$

$$\boxed{f_x = pAV^2}$$



$$f_y = -[\{ pQ_2V + pQ_3(-V) \} - pQ(0)] - \textcircled{1}$$

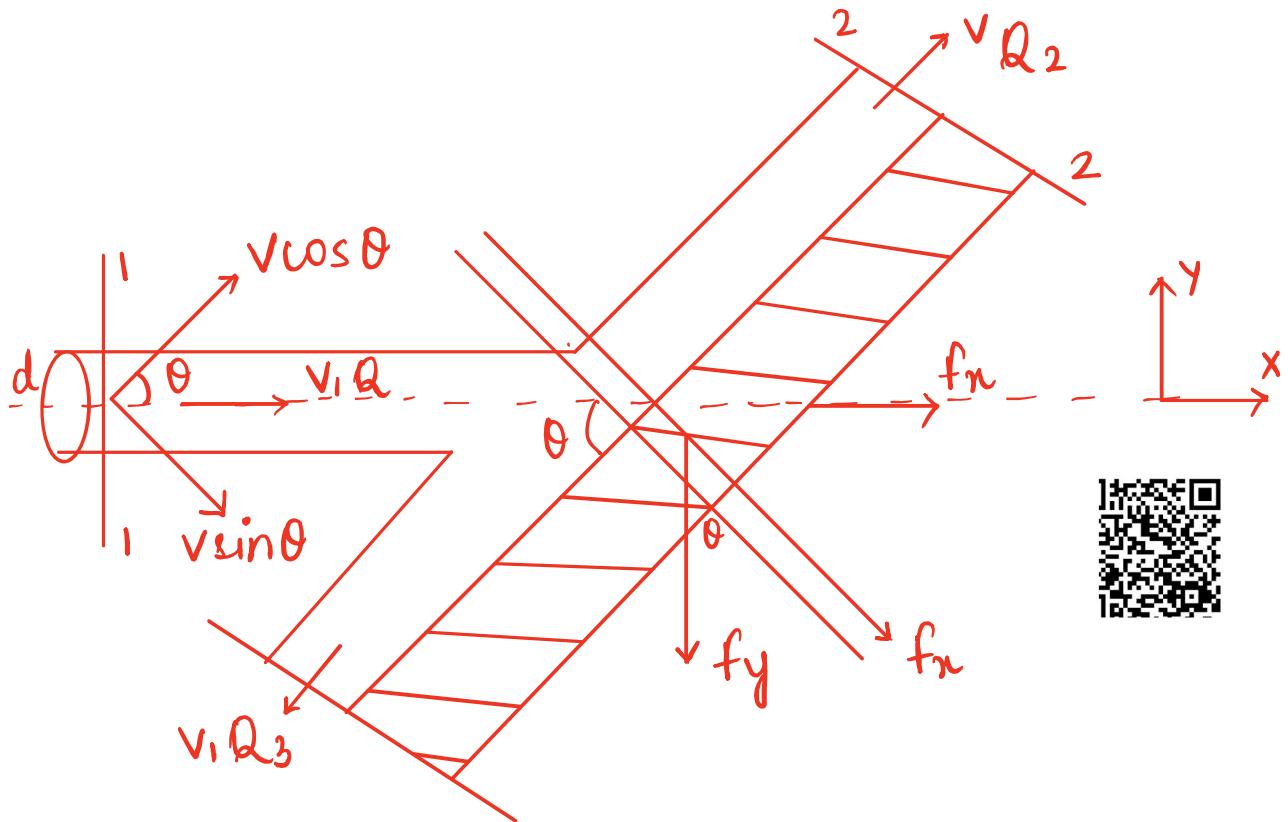
$$Q_2 = Q_3 \quad \textcircled{11}$$

from \textcircled{1} and \textcircled{11}, $f_y = 0$.

$$\text{Also, } Q = Q_2 + Q_3$$

$$\Rightarrow Q_2 = Q_3 = \frac{Q}{2}.$$

b) Plate held at an inclination to the jet



$$f_n = -[\rho Q(0) - \rho Q v \sin \theta] = \rho Q v \sin \theta = \rho A V^2 \sin \theta.$$

Also,

$$f_x = f_n \sin \theta = \rho A V^2 \sin^2 \theta.$$

$$f_y = f_n \cos \theta = \rho A V^2 \sin \theta \cos \theta.$$

Now, $f_s = 0$.

$$f_s = -[\{\rho Q_2 v + \rho Q_3 (-v)\} - \rho Q v \cos \theta] = 0.$$

$$Q_2 - Q_3 = Q \cos \theta \quad \text{--- } \textcircled{I}$$

$$Q_2 + Q_3 = Q \quad \text{--- } \textcircled{II}$$



from \textcircled{I} and \textcircled{II}

$$Q_2 = \frac{Q}{2} (1 + \cos \theta)$$

$$Q_3 = \frac{Q}{2} (1 - \cos \theta).$$

Question: A flat plate, hinged about its top edge is suspended vertically and weighing 10 kN. A jet of water 50 mm in dia and 50 m/sec velocity strikes normal to it at its mid point.

Compute

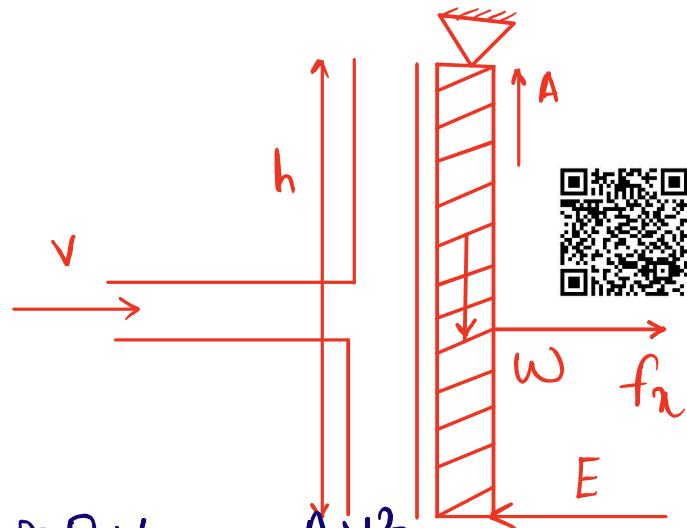
- The horizontal force that must be applied to its bottom edge to keep it vertical.
- The angle of deflection, where it's stage in equilibrium.

Answer: a) for plate to remain vertical.

$$\sum M_A = 0$$

$$f \cdot h = f_x \cdot \frac{h}{2}$$

$$f = \frac{f_x}{2}$$



$$f_x = -pQ(0-v) = pQv = pAv^2$$

$$f = \frac{pAv^2}{2}$$

$$= 10^3 \times \frac{\pi}{4} \times (50)^2 \times 50^2 \times \frac{1}{2} \times 10^{-6} \times 10^{-3}$$

$$= 2.454 \text{ kN.}$$

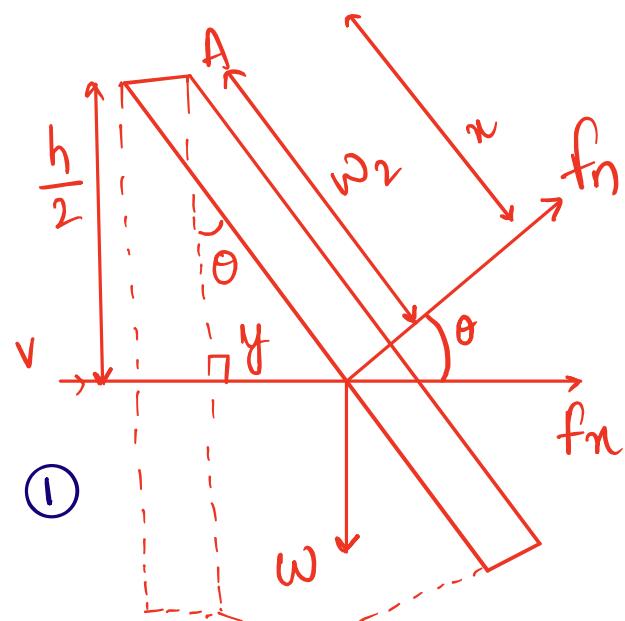
b) At equilibrium $\sum M_A = 0$.

$$w_y - f_n \cdot n = 0.$$

$$w \cdot \frac{h}{2} \sin \theta$$

$$= f_n \cdot \frac{h}{2 \cos \theta}$$

$$\sin \theta = \frac{f_n}{w} \cdot \sec \theta \quad \text{--- } ①$$



$$f_n = -[pQ(0) - v \cos \theta)] = pQv \cos \theta \\ = pAv^2 \cos \theta \quad \text{--- (II)}$$

from ① and ②

$$\sin \theta = \frac{pAv^2 \cos \theta \cdot \sec \theta}{\omega}$$

$$\theta = \sin^{-1} \left[10^3 \times \frac{\pi}{4} \left(50 \times 10^{-3} \right)^2 \times 50^2 \times \frac{1}{10 \times 10^3} \right]$$

$$\theta = 29.398^\circ .$$

