

AIR-1 Notes

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Handwritten notes by



Kartikay Kaushik

AIR-1 ESE 2021

IES Master classroom Student

Engg. Drawing

Syllabus

- 1) Engg. Curves] Mathematical.
- 2) Theory of projection]
- 3) Projection of point]
- 4) Projection of line] Common sense and aptitude
- 5) Projection of surface]
- 6) Projection of Solid]
- 7) Development of Surfaces.] Aptitude.

Ch-1 Engineering Curves

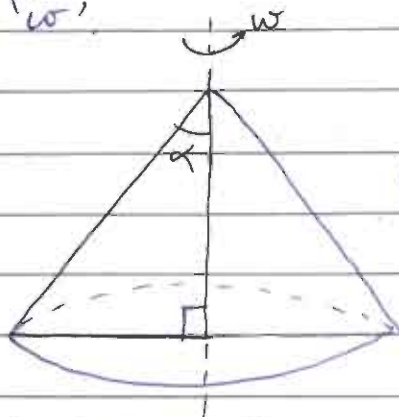
1) Conic Sections

2) Special Curves

1) Conic Sections

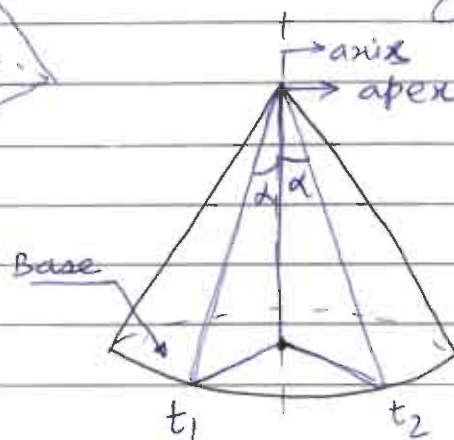
(a) Conic section defined as section of cone

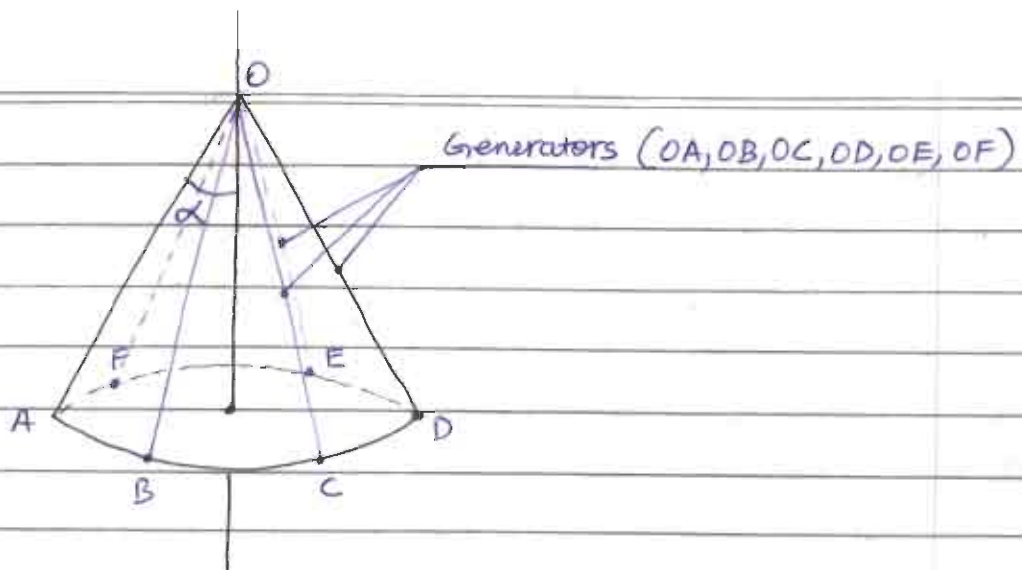
⇒ Consider a right angled Δ rotated about its altitude at a certain angular velocity ' ω '



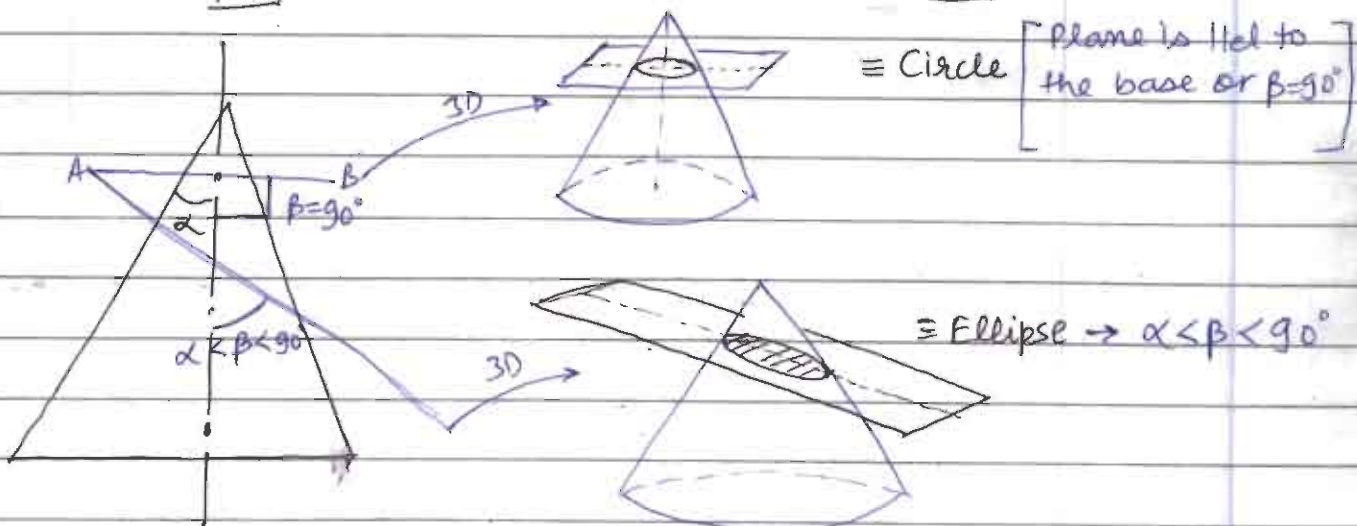
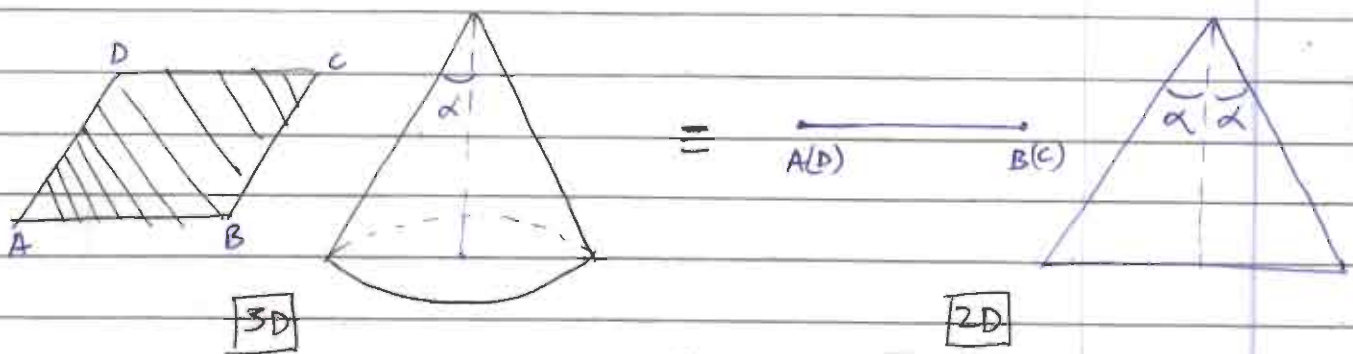
$\alpha \rightarrow$ semi-apex angle.

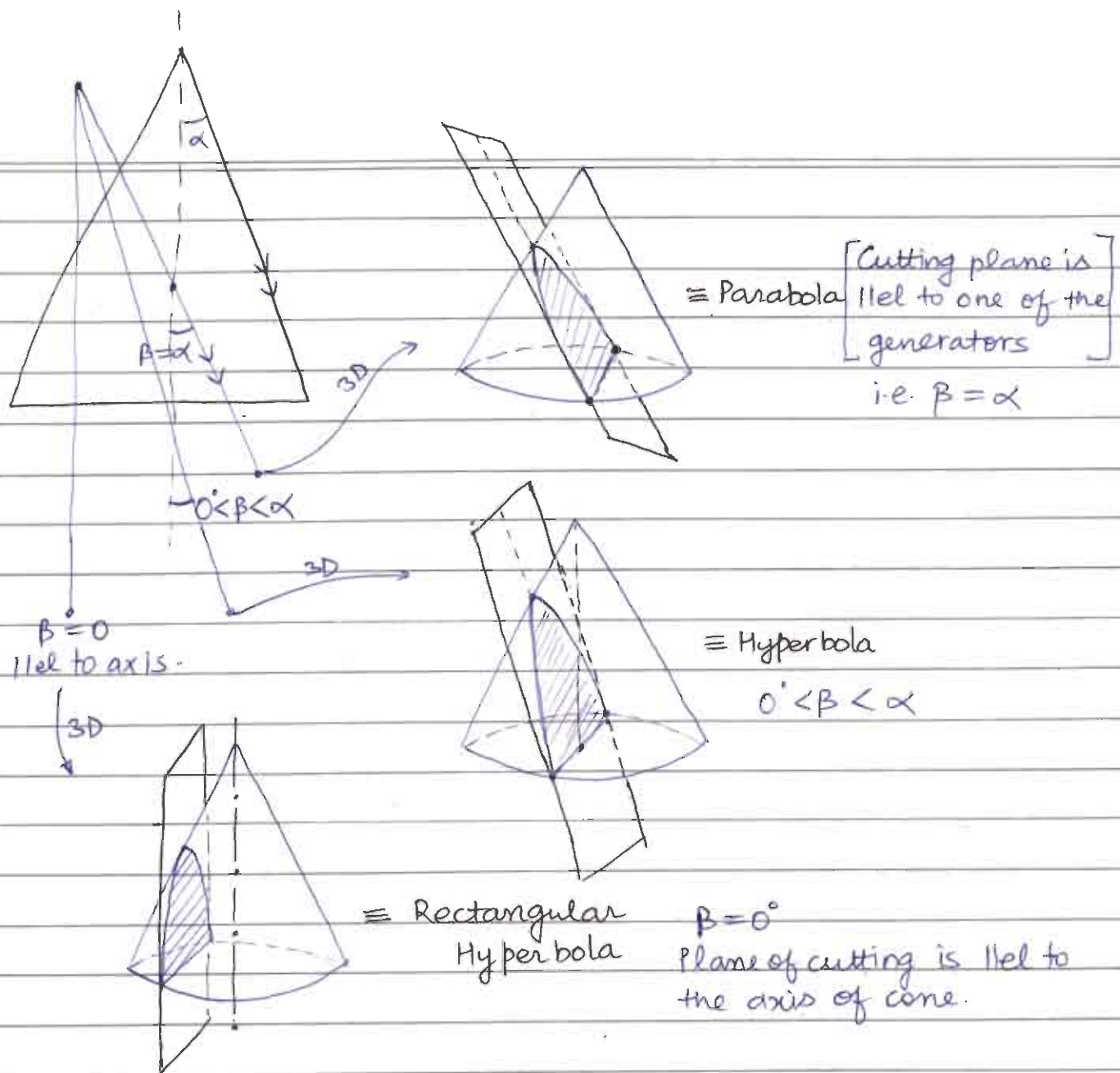
Solid of Revolution \rightarrow Right Circular Cone





- ⇒ Any imaginary line joining the apex to the circumference of base of the circle is known as a generator.
- ⇒ Cone is a solid of revolution i.e. it appears as a solid cone only when a triangular plane is rotated about its altitude.
eg - Cylinder and sphere. → Single Curved surface.
- ⇒ A conic section is the section of a right circular cone obtained by cutting the cone in different ways by a straight plane known as cutting plane.





NOTE: $\rightarrow \beta = 90^\circ \rightarrow$ Circle

$\rightarrow \alpha < \beta < 90^\circ \rightarrow$ ellipse

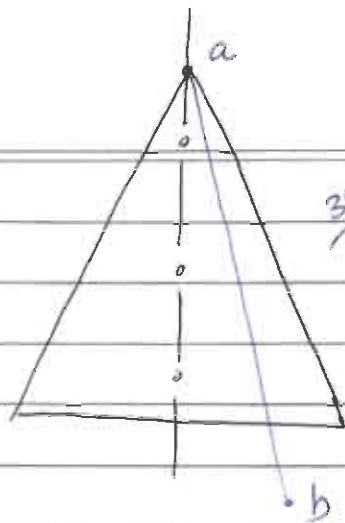
$\rightarrow \beta = \alpha \rightarrow$ Parabola

$\rightarrow 0^\circ < \beta < \alpha \rightarrow$ Hyperbola

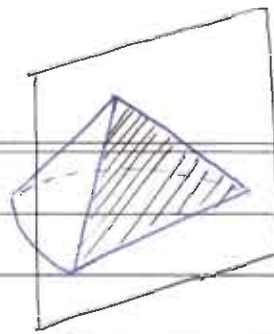
$\rightarrow \beta = 0^\circ \rightarrow$ Rectangular Hyperbola.

\rightarrow Circle and ellipse cuts all the generators of a cone whereas parabola, hyperbola and rectangular hyperbola does not cut all the generators.

\rightarrow If the cutting plane cuts the right circular cone in such a way such that one end of the cutting plane passes through apex, then an isosceles Δ is formed.



3D →



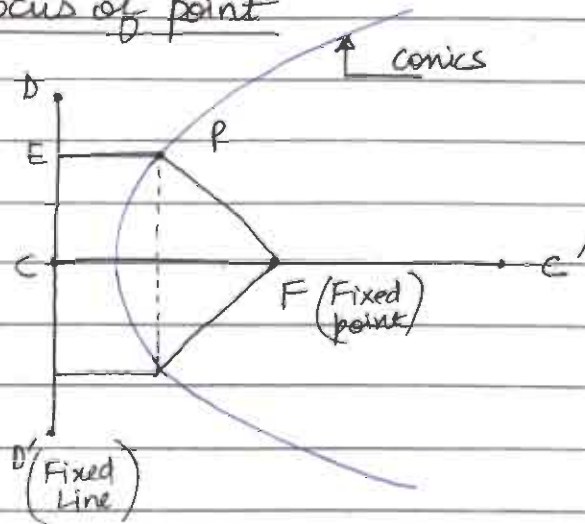
≅ isosceles Δ.

⇒ Conic sections as locus of point

$CC' \rightarrow$ axis of cone

$DD' \rightarrow$ Directrix

$F \rightarrow$ Focus.



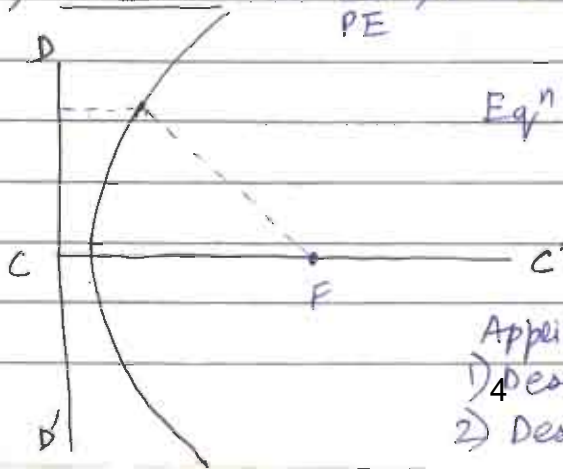
$$e = \frac{PF}{PE} = \text{const.}$$

↳ eccentricity.

→ A conic is defined as the locus of a point moving in a plane such that the ratio of its distance from fixed pt (called focus) to a fixed line called directrix is always a constant known as eccentricity.

$$\text{Eccentricity, } e = \frac{\text{Distance of point from focus}}{\text{Distance of point from directrix.}}$$

(Case 1) $PF > PE \rightarrow \frac{PF}{PE} > 1 \rightarrow e > 1 \rightarrow$ Hyperbola



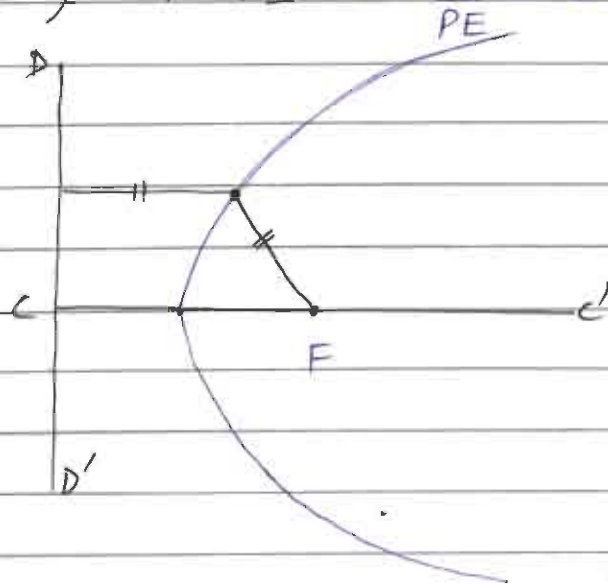
$$\text{Eq}^n \rightarrow \frac{x^2}{a^2} - \frac{y^2}{b^2} = 1$$

$$b^2 = (e^2 - 1)a^2$$

Application:

- 1) Designing of cooling towers
- 2) Designing of flower vases.

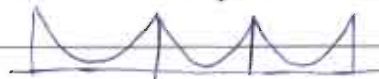
Case 2) $PF = PE \rightarrow \frac{PF}{PE} = 1 \rightarrow e = 1 \rightarrow \text{Parabola}$



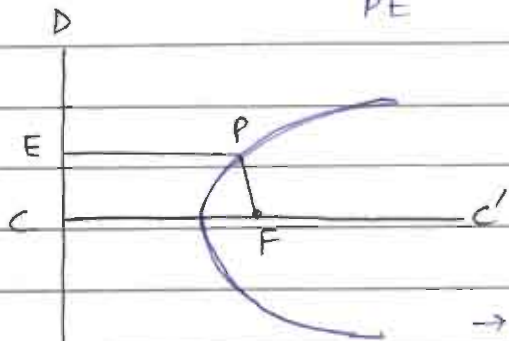
$$\text{Eq}^n \rightarrow y^2 = 4ax$$

→ Application:

- Path of trajectory
- Solar concentrator
- Parabolic reflectors.
- Headlights.



Case 3) $PF < PE \rightarrow \frac{PF}{PE} < 1 \rightarrow e < 1 \rightarrow \text{ellipse}$

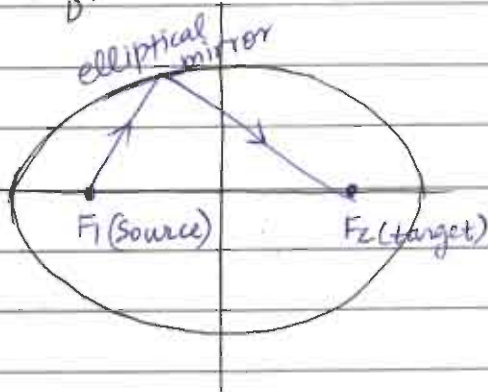


$$\text{Eq}^n \rightarrow \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$$

$$b^2 = (1 - e^2)a^2$$

→ Application:

- Designing of bridges, arches
- Use of lithotripsy



Laposcopic
Surgery to treat
Kidney stones.

NOTE: As $e < 1$,
as $e \rightarrow 0$

Eqⁿ for $e < 1 \Rightarrow \frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ where $b^2 = (1 - e^2)a^2$

$$\boxed{x^2 + y^2 = a^2} \quad \leftarrow \quad b^2 = a^2$$

\rightarrow circle $\rightarrow e = 0$

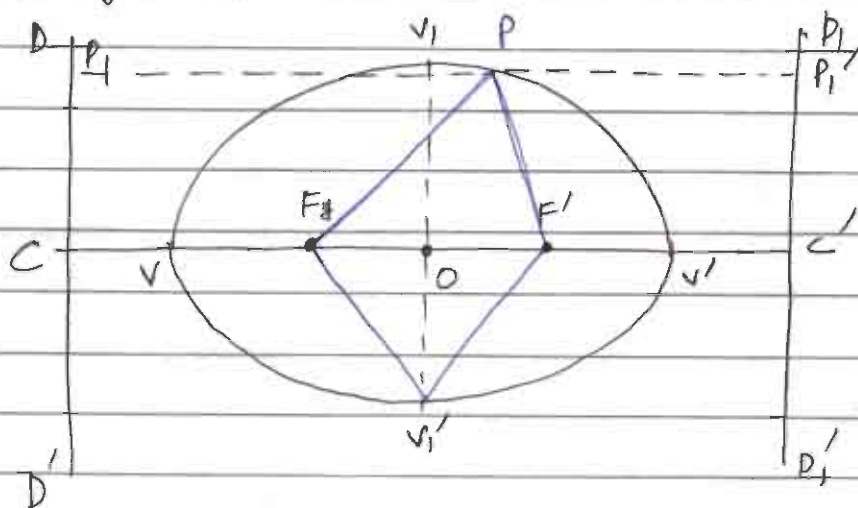
\Rightarrow 3 conic sections:

- 1) Hyperbola
- 2) Parabola
- 3) Ellipse.

\rightarrow Circle is the 4th type of conic section and it is a special case of ellipse having eccentricity = 0.

\rightarrow Isosceles Δ is not a conic section as it does not form second order equation.

\Rightarrow Properties of conics



$DD', D_1D_1' \rightarrow$ Directrix

$vv' \rightarrow$ major axis

$v_1v_1' \rightarrow$ minor axis

$O \rightarrow$ Centre of ellipse.

~~$\Rightarrow PF + PF' = ePP_1 + ePP_1' = e(CG')$~~

$\Rightarrow PF + PF' = FV' + F'V = FV' + VF = vv' = \text{major axis}$

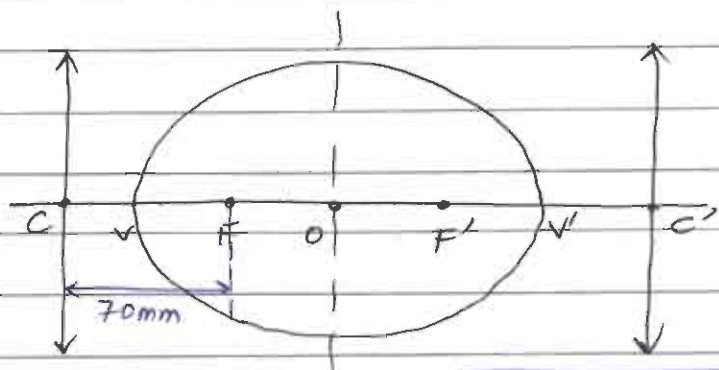
$\Rightarrow \underbrace{Fv_1' + F'v_1'}_{\text{equal}} = vv' \Rightarrow Fv_1' = F'v_1' = Fv_1 = F'v_1 = \frac{vv'}{2}$

→ Ellipse is also defined as the locus of point which moves in a plane such that the sum of its distance from 2 fixed points is always constant and it is equal to major axis

→ The distance of any end of the minor axis from focus is half of major axis.

Q- In the figure shown if distance of focus (F) from the directrix is 70mm, $e = 3/4$

- (a) Find $V'F$
 (b) Find FF' , VV' , CC'
 (c) Find Relation b/w (ii)



$$(a) \quad e = \frac{V'F}{V'C} = \frac{3}{4} \Rightarrow \frac{V'F}{V'F + 70} = \frac{3}{4} \Rightarrow \boxed{V'F = 210 \text{ mm}}$$

$$(b) \quad e = \frac{VF}{VC} = \frac{3}{4} \Rightarrow \begin{aligned} VF &= 30 \text{ mm} \\ VC &= 40 \text{ mm} \end{aligned}$$

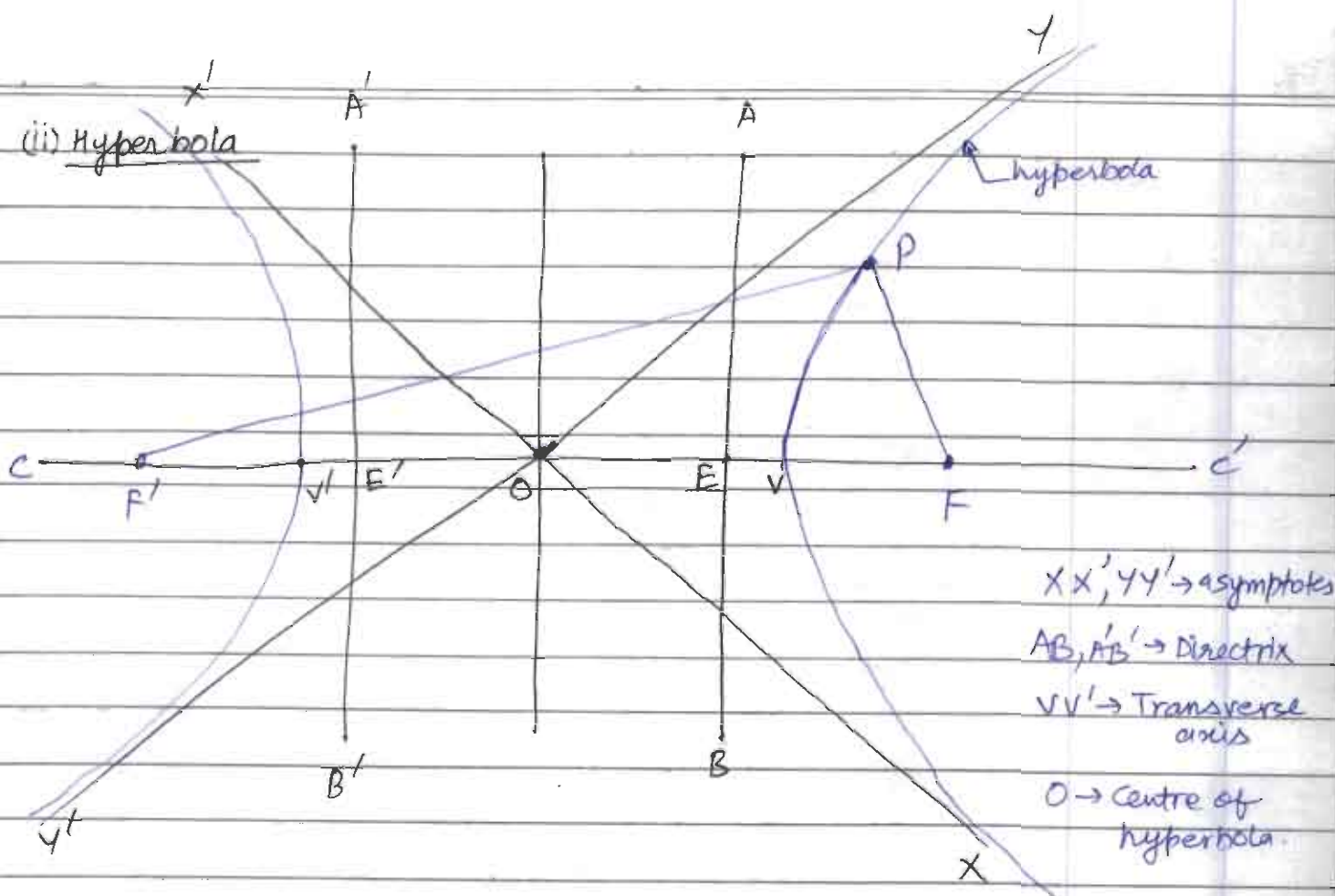
$$\begin{aligned} FF' &= VV' - 2(VF) \Rightarrow FF' = V'F + VF - 2VF = V'F - VF \\ &\Rightarrow FF' = 210 - 30 = 180 \text{ mm} \end{aligned}$$

$$VV' = V'F + VF = 210 + 30 = 240 \text{ mm}$$

$$CC' = VV' + 2VC = 240 + 2 \times 40 = 320 \text{ mm}$$

$$\frac{FF'}{VV'} = \frac{VV'}{CC'}$$

$$VV' = \sqrt{FF' \times CC'} \quad \text{geometric mean}$$



\rightarrow A hyperbola is locus of point which moves in a plane so that the difference between the point and the 2 focus is always constant and it is equal to transverse axis.

$$PF' - PF = VF' - VF$$

$$= VV' + V'F' - VF = VV'$$

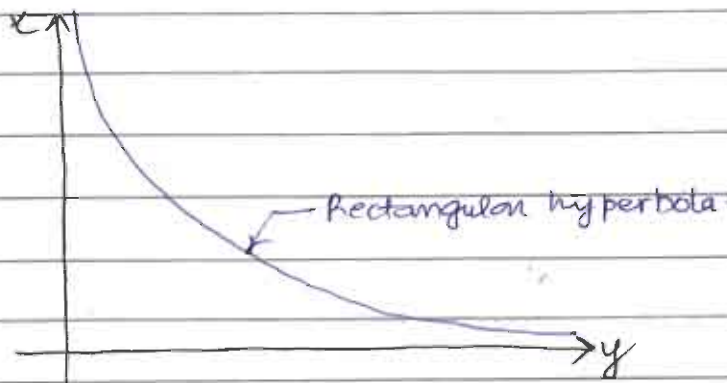
NOTE:



$$\textcircled{1} \Rightarrow \frac{FF'}{VV'} = \frac{VV'}{EE'} = e \Rightarrow \boxed{VV' = \sqrt{FF' \times EE'}}$$

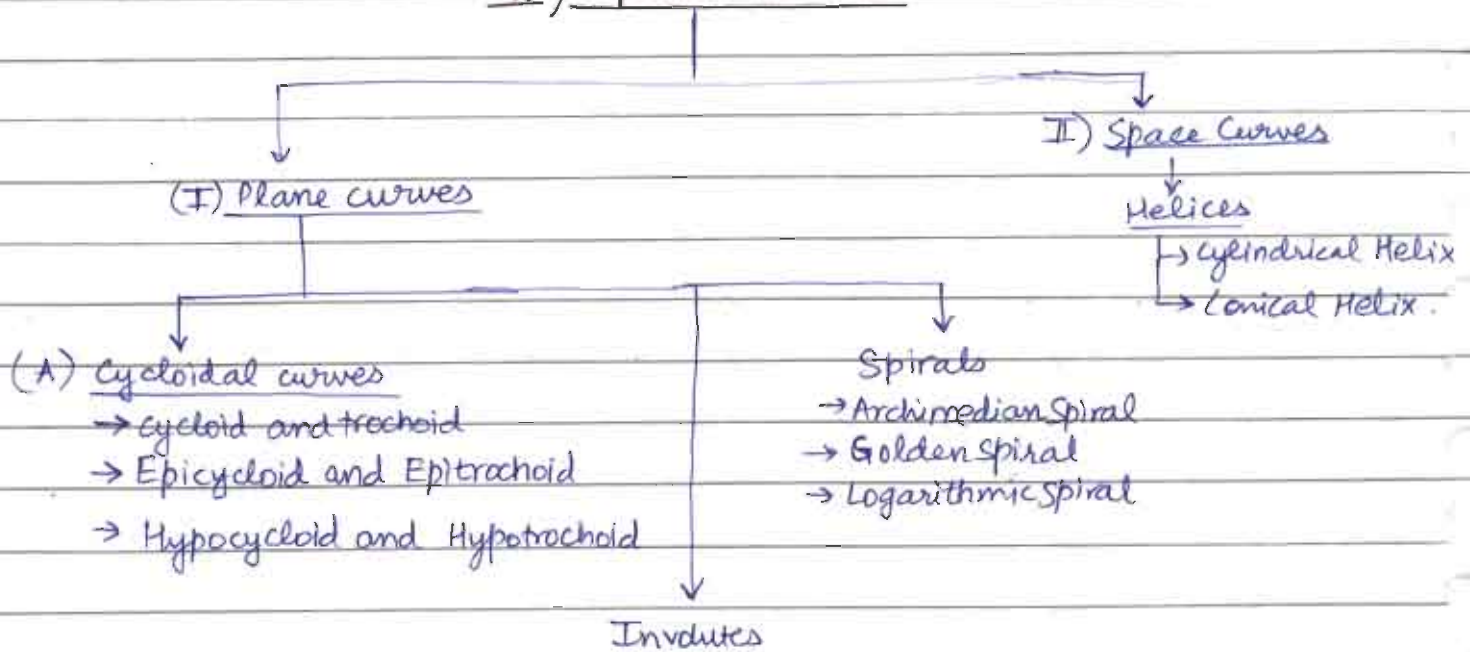
\Rightarrow If angle between asymptotes is 90° then hyperbola is known as rectangular hyperbola or equilateral hyperbola, having eccentricity $= \sqrt{2}$

Ex: $xy = \text{constant} \Rightarrow y = \frac{R}{x} \Rightarrow y \propto \frac{1}{x}$



\rightarrow Boyle's Law $\Rightarrow pV = \text{constant}$.

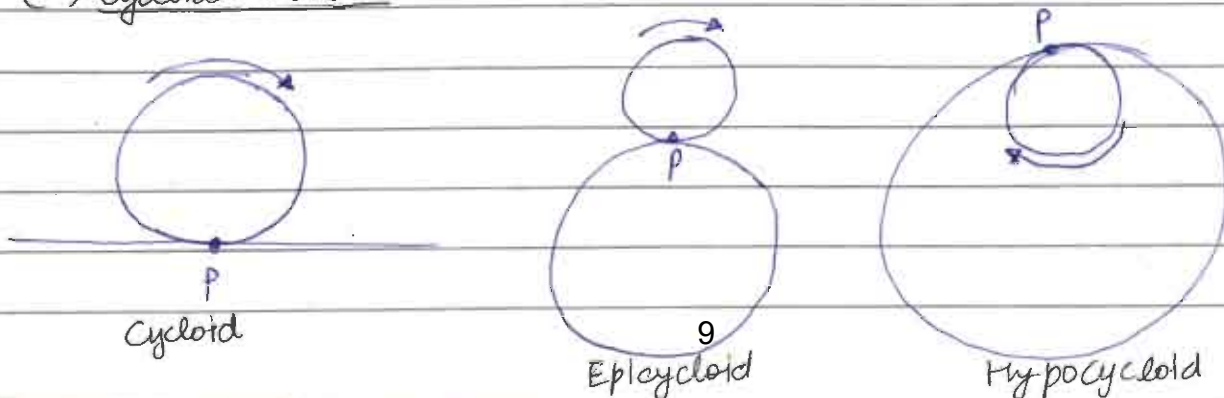
** II) Special Curves



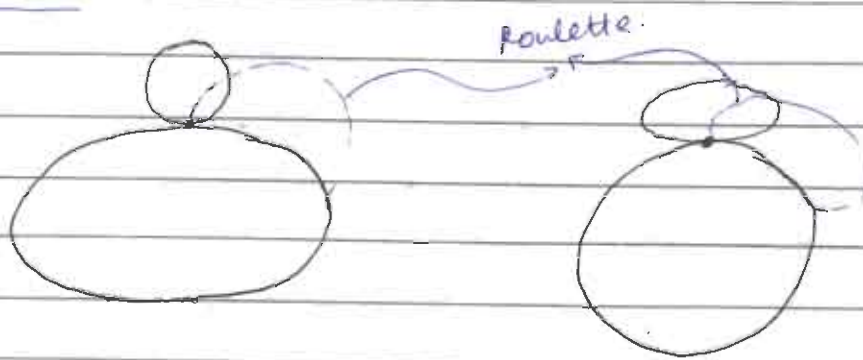
\Rightarrow Plane curves:

\rightarrow Curve that is drawn on a 2D plane.

(A) Cycloidal curve

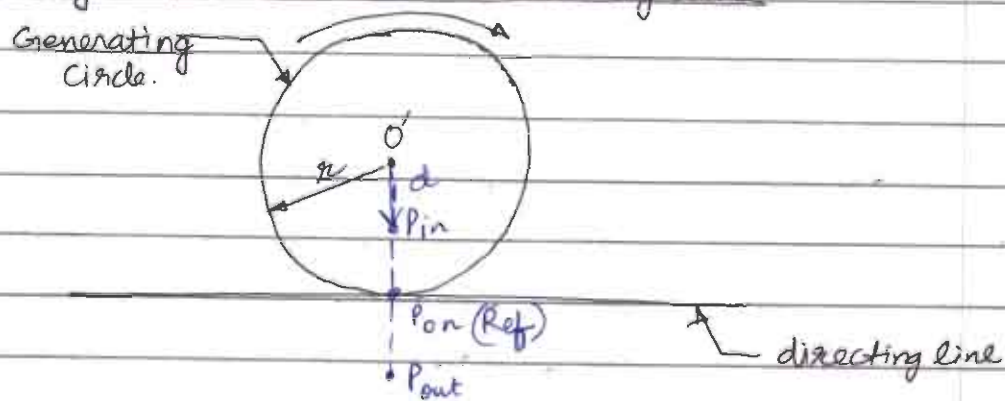


→ When one curve rolls over another curve without slipping or sliding, the path of any point of the rolling curve is called as roulette.



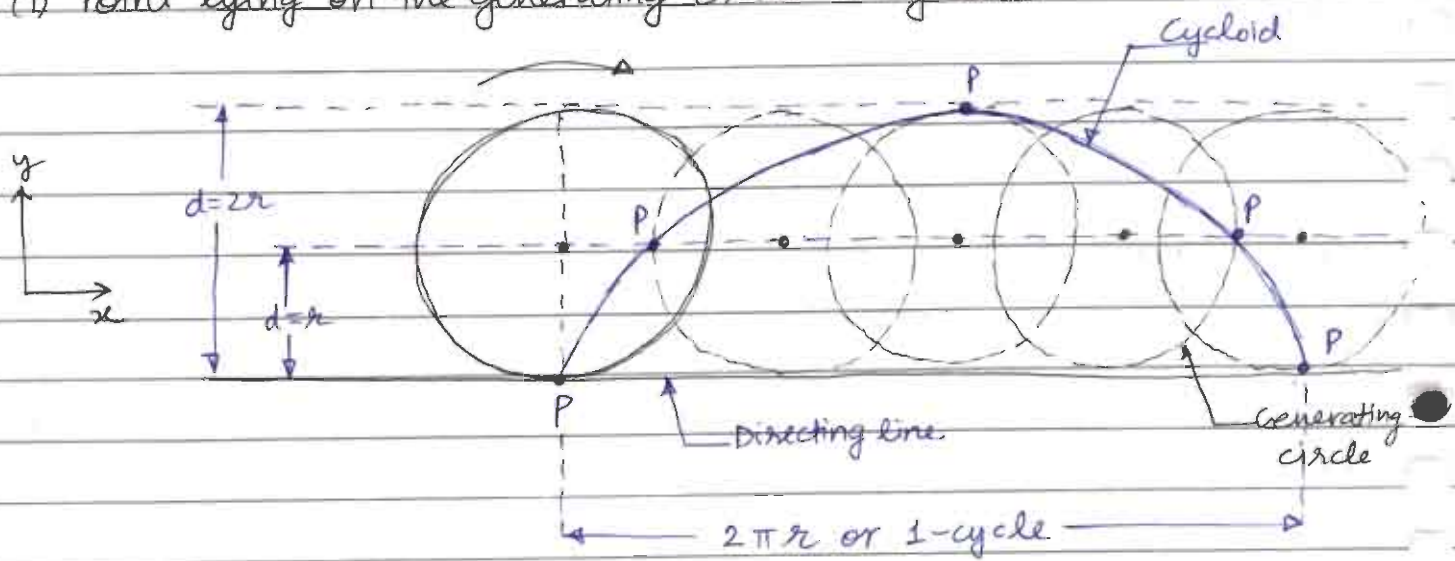
→ When a rolling curve is a circle known as generating circle and the curve on which it rolls is either a straight line known as directing line or rolls on a circle known as directing circle, the locus is known as cycloidal curve.

⇒ Generating circle rolls on a directing line

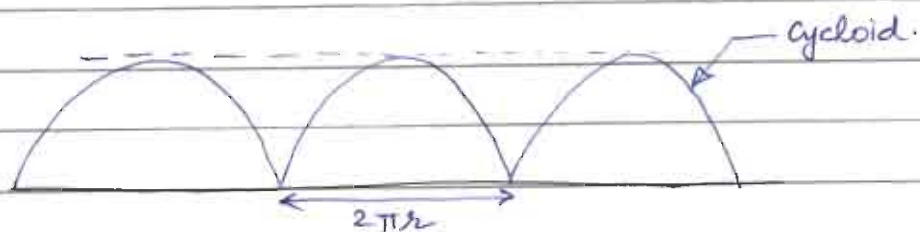


- if $d = r \rightarrow$ cycloid
- $d > r \rightarrow$ Superior trochoid
- $d < r \rightarrow$ Inferior trochoid.

(i) Point lying on the generating circle \rightarrow Cycloid.



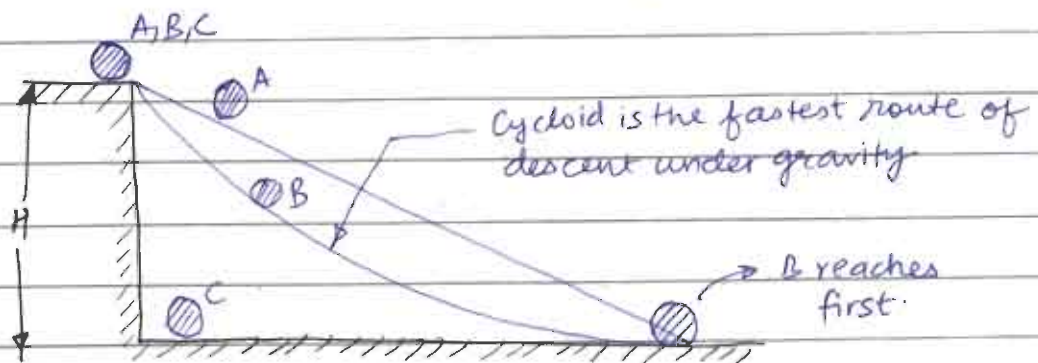
Locus of P



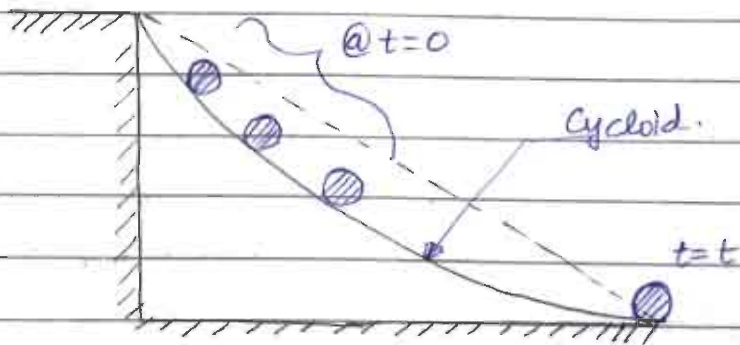
\rightarrow In one complete cycle of rotation only 1 cycloid is formed.

Application

1) Cycloid is the solution to Brachistochrone problem.

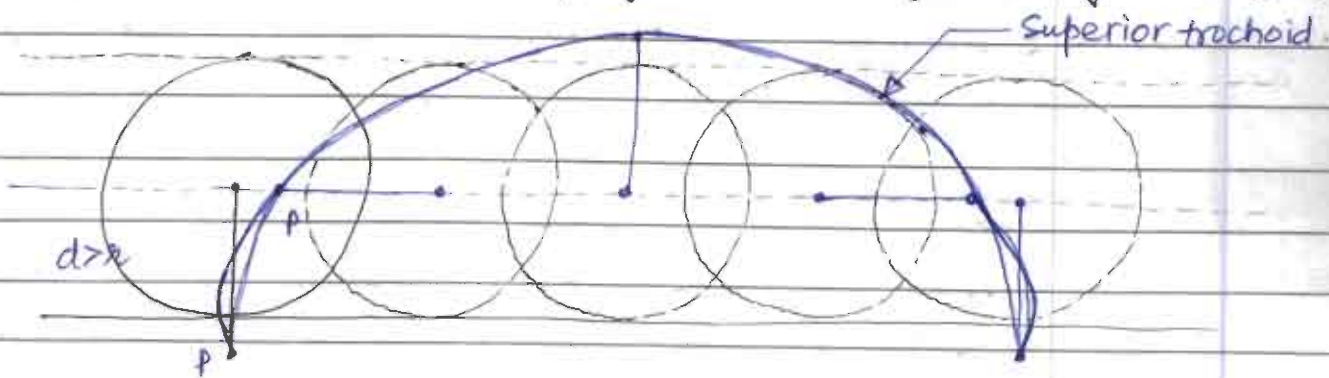


2) Cycloid is the solution to tautochrone problem.

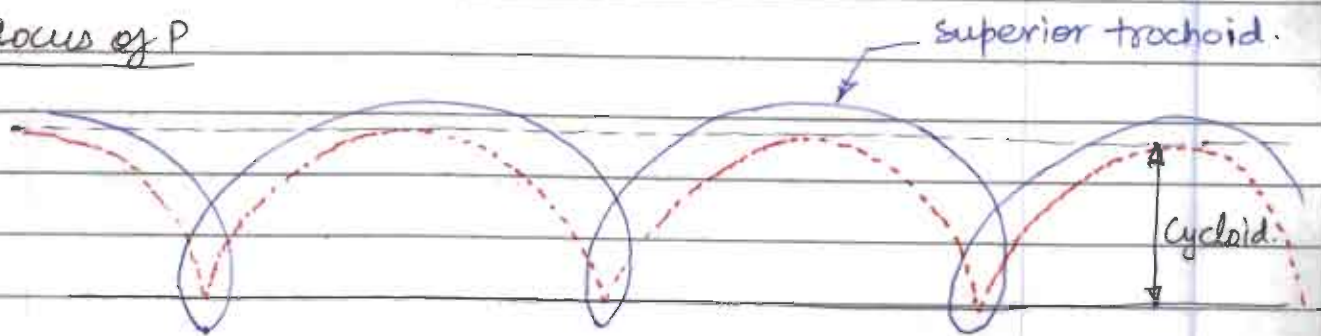


⇒ The time period of an object in descent without friction inside the curve does not depend on the objects starting position.

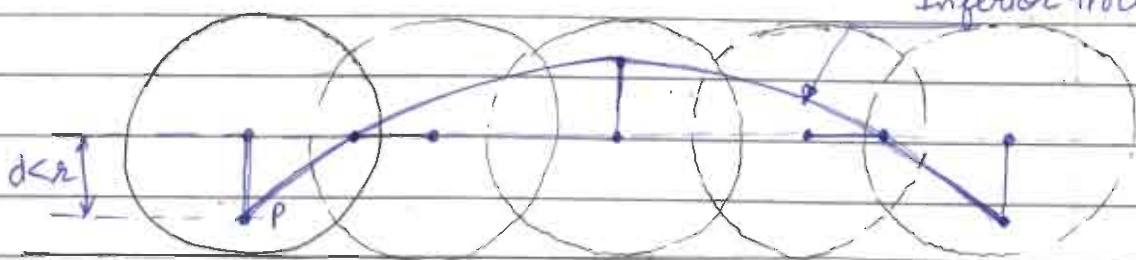
(ii) Superior Trochoid → Point lying outside the generating circle ($d > r$)



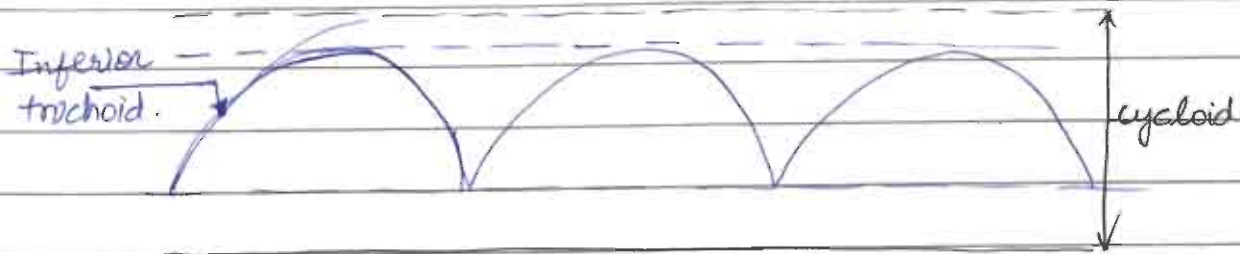
Locus of P



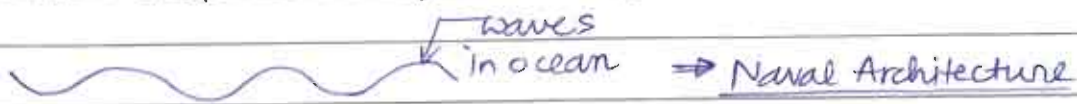
(iii) Inferior trochoid → Point lying inside the generating circle ($d < r$)



Locus of P

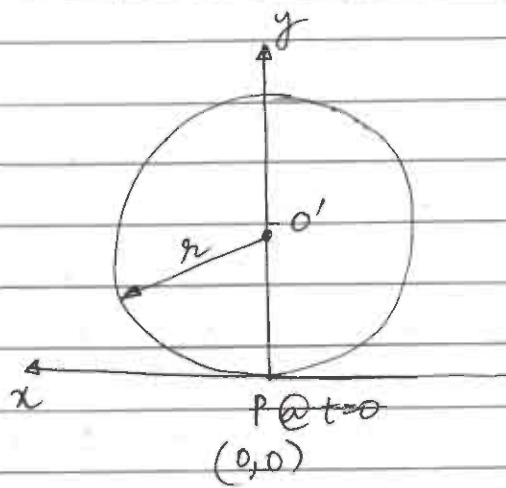


NOTE: Application of both inferior and superior

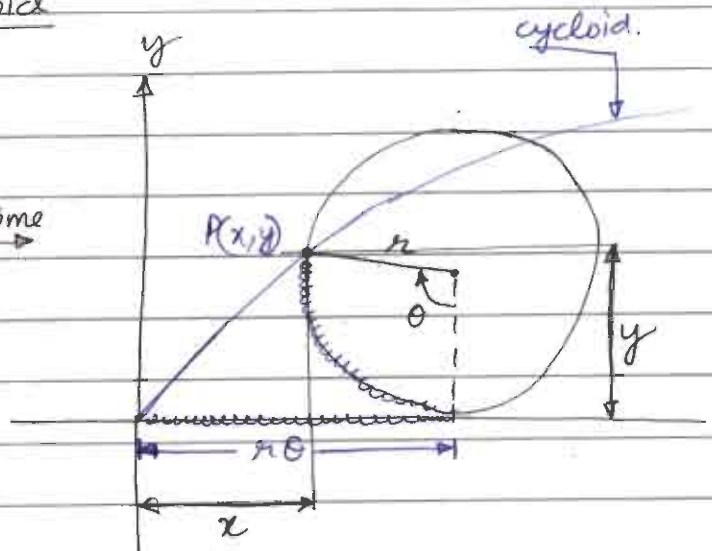


→ It approximates wave profile used in naval architecture

⇒ Parametric equations of cycloid

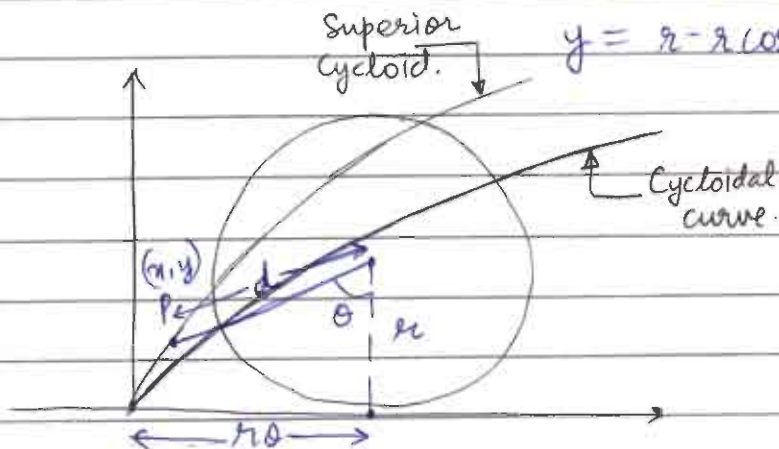


After time t



$$x = r\theta - r\sin\theta$$

$$y = r - r\cos\theta$$



In general,
 $x = r\theta - d\sin\theta$
 $y = r - d\cos\theta$

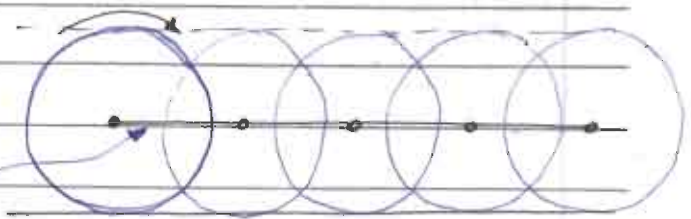
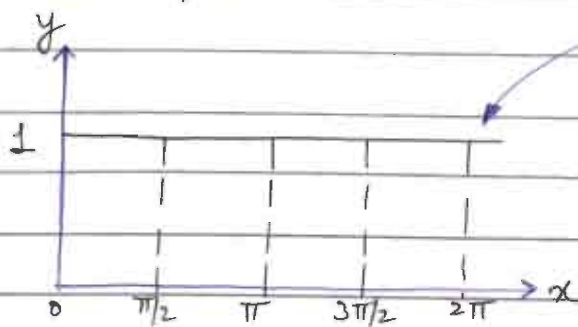
valid for $d < r$
 $d = r$
 $d > r$

- NOTE:
- (i) if $d > r \rightarrow$ superior trochoid
 - (ii) if $d = r \rightarrow$ cycloid
 - (iii) if $d < r \rightarrow$ inferior trochoid
 - (iv) if $d = 0 \rightarrow$ straight line.

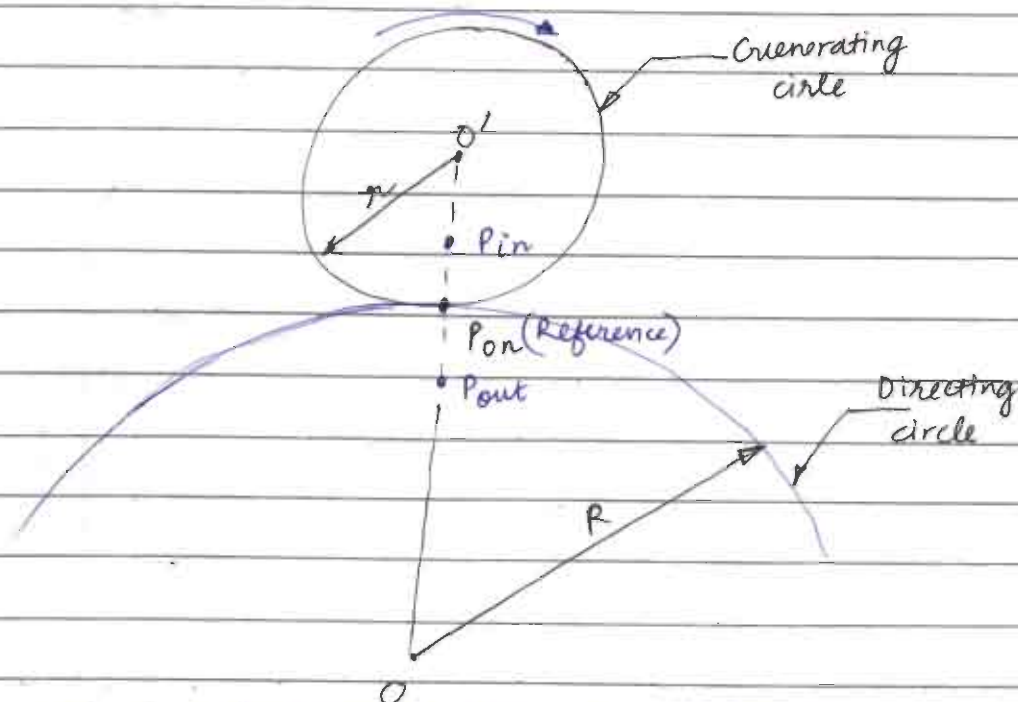
$$x = r\theta$$

$$y = r$$

For $r = 1$



B) Generating circle rolls outside the directing circle



Let d is distance of point from centre of generating circle:

- (i) if $d = r \rightarrow$ epicycloid
- (ii) if $d > r \rightarrow$ superior epitrochoid
- (iii) if $d < r \rightarrow$ inferior epitrochoid.