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STRENGTH OF MATERIALS

- Theory
- Explanation
- Derivation
- Example
- Shortcuts
- Previous Years Question With Solution

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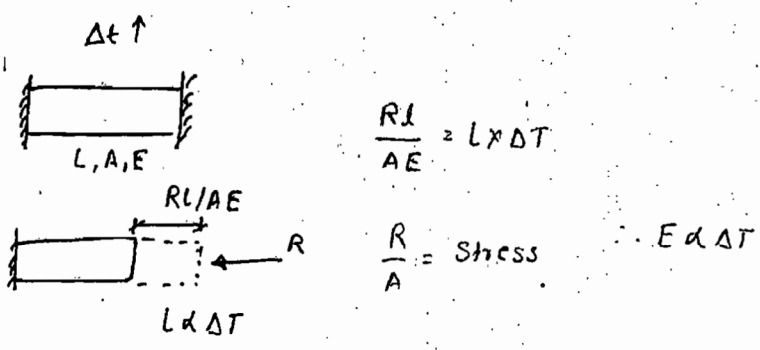
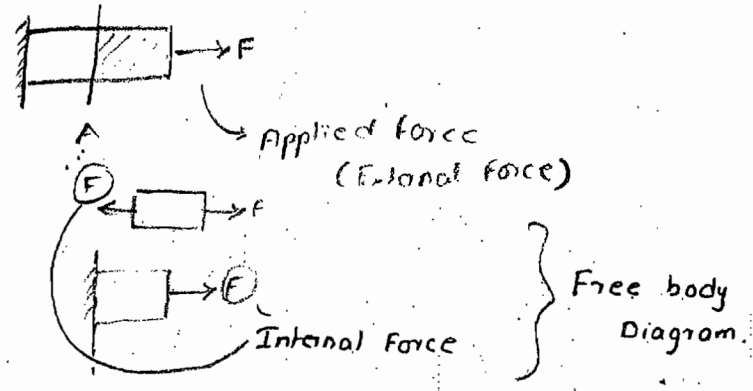
STRENGTH OF MATERIAL

SHIVAM SINGH
CIVIL ENGINEER

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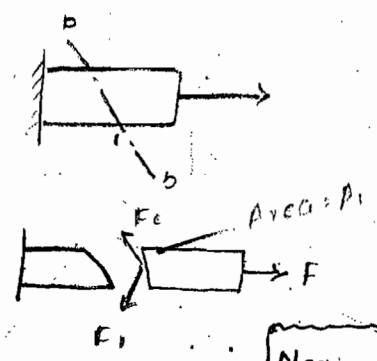
→ Stresses develop in a body on account of restraining force or restrain deformation.

$$\text{Stress} = \frac{\text{Restrain force}}{\text{Area}} = \frac{F}{A}$$



* Stresses are two types:-

- 1) Normal stress - stress perpendicular to the section
- 2) Shear stress - stress along the section.

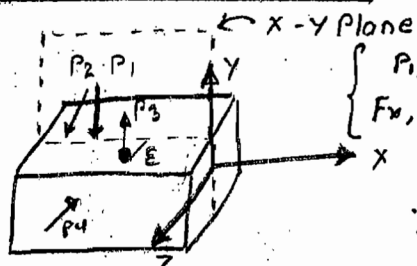


$$\therefore \text{Normal stress} = \frac{F_1}{A_1} = \sigma$$

$$\therefore \text{Shear stress} = \frac{F_2}{A_1} = \tau$$

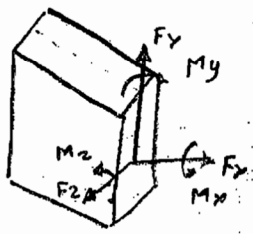
②

* Various types of internal forces :-



$P_1, P_2, P_3, \& P_4 \rightarrow$ External force
 $F_x, F_y, F_z, M_x, M_y, M_z =$ Internal Force.

- $\therefore F_x =$ Axial force
- $F_y, F_z =$ Transverse shear force
- $M_x =$ Torsional moment
- $M_y, M_z =$ Bending moment
- $M_x =$ Twisting moment

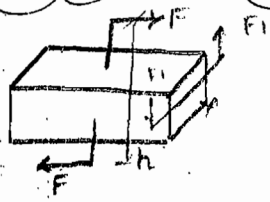


\therefore Direction of moment is given Right hand thumb rule.

\rightarrow Under general loading condition max. no. of internal force is (6).

* Note:-

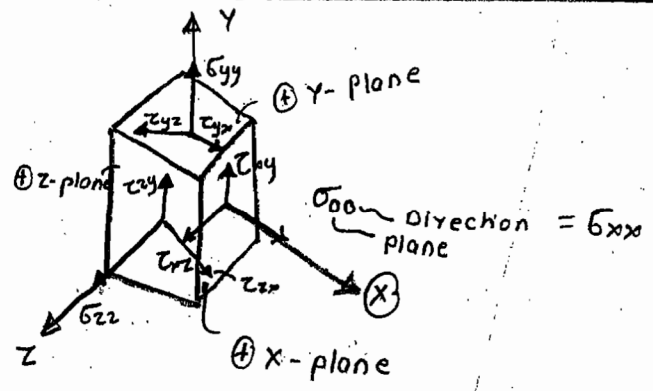
- $F_x \rightarrow$ Axial force \rightarrow Generate axial stress \rightarrow Normal stress
- $F_y, F_z \rightarrow$ Transverse shear force \rightarrow Generate transverse shear stress \rightarrow Shear stress
- $M_y, M_z \rightarrow$ Bending moment \rightarrow Generate bending stress \rightarrow Normal stress
- $M_x \rightarrow$ Twisting moment \rightarrow Generate torsional shear stress \rightarrow Shear stress.



$\therefore \{ Fh = \text{Bending couple} \}$
 $\{ Fx = \text{Torsional couple} \}$

- \rightarrow If the structure and the loading are in the same plane, the structure is called planar structure or 2D structure.
- \rightarrow Under 2D or planar condition max. no. of internal forces at any section is (3) (F_x, F_y, M_y)
 \therefore Axial Force, Transverse force, Bending moment.

Stresses under general loading condition:-



⊕ x-plane: Outward normal to the plane is in x-direction.

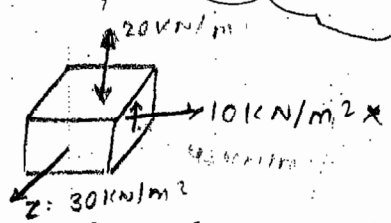
→ Under general loading condition, at any point we can have maximum of (9) stress component. Out of these (3) are normal stresses ($\sigma_{xx}, \sigma_{yy}, \sigma_{zz}$) & (6) shear stresses ($\tau_{xy}, \tau_{yx}, \tau_{yz}, \tau_{zy}, \tau_{zx}, \tau_{xz}$).

Note: (Sign convention)

Plane	Direction	Sign
⊕	⊕	= ⊕
⊕	⊖	= ⊖
⊖	⊕	= ⊖
⊖	⊖	= ⊕

→ +ve plane is the plane, the outward normal to which points in +ve co-ordinate direction.

NOTE:-

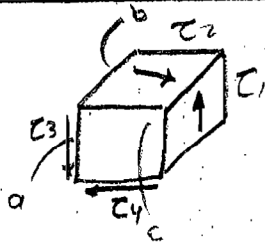


$\sigma_{xx} = \oplus 10 \text{ kN/m}^2$
 $\sigma_{yy} = \ominus 20 \text{ kN/m}^2$
 $\tau_{xy} = \oplus 40 \text{ kN/m}^2$
 $\tau_{zx} = \ominus 30 \text{ kN/m}^2$

{ Tensile stress ⊕ve
 Compressive stress ⊖ve }

4

* Equality of shear stresses:-



$$\begin{aligned} \sum F_v = 0 & \\ \tau_1 ab = \tau_3 ab = 0 & \\ \tau_1 = \tau_3 & \end{aligned} \quad \left\{ \begin{aligned} \sum F_H = 0 \\ \tau_2 bc - \tau_4 bc = 0 \\ \tau_2 = \tau_4 \end{aligned} \right.$$

$$\begin{aligned} \sum M = 0 \\ (\tau_2 bc)a - (\tau_1 ab)c = 0 \end{aligned}$$

$$\tau_1 = \tau_2$$

- Shear stresses on opposite faces are equal but opposite in direction & it follows from forces.
- Shear stresses on adjacent plane are equal and they are directed such that either both of them point toward the junction or they point away from the junction.
- This follows from moment equilibrium.
- Hence under general loading condition:-

$$\tau_{xy} = \tau_{yx}$$

$$\tau_{yz} = \tau_{zy}$$

$$\tau_{zx} = \tau_{xz}$$

- Thus under general loading condition maximum number of distinct stress component at a point will be (6)

$$\underline{\sigma_{xx}}, \underline{\sigma_{yy}}, \underline{\sigma_{zz}}, \left\{ \begin{aligned} \tau_{xy} = \tau_{yx} \\ \tau_{yz} = \tau_{zy} \\ \tau_{zx} = \tau_{xz} \end{aligned} \right\}^*$$

* STRESS TENSION MATRIX:-

$$\underline{\sigma} = \begin{bmatrix} \sigma_{xx} & \tau_{xy} & \tau_{xz} \\ \tau_{yx} & \sigma_{yy} & \tau_{yz} \\ \tau_{zx} & \tau_{zy} & \sigma_{zz} \end{bmatrix} \begin{matrix} \rightarrow \text{Plane} \\ \downarrow \text{Dir}^n \\ \rightarrow \text{Stress Tension Matrix} \end{matrix}$$

- Stress tension matrix is a symmetrical matrix. Symmetry of stress tension matrix is on account of moment equilibrium.

Note: $3^n = \text{No. of element in tension matrix.}$ Then (n) is order of tension matrix.
 → Stress is a 2 orderd tension/Tensor.

* Note:-

- Strain & moment of inertia is also 2nd order tension.

- Stress is not a vector quantity because/because although it has magnitude &

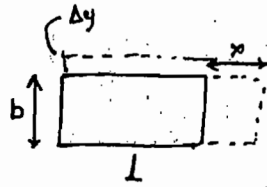
5)

* STRAIN

o strain are of two types:-

1) Normal Strain - Deformation per unit length.

2) Shear Strain

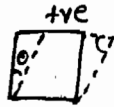
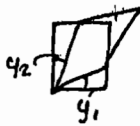


$$\{E = \text{Normal Strain}\} = \frac{\Delta L}{L}$$

Change in length
Actual Length.

$$E_{xx} = \frac{\Delta L}{L} = \text{Normal stress/strain in } x\text{-direction}$$

$$E_{yy} = \frac{\Delta y}{b} = \text{Normal strain in } y\text{-direction.}$$



$$\{\gamma_1 + \gamma_2 = \tau = \text{Shear Strain.}\}$$

→ If the angle between ⊕ faces decreases the shear strain is taken as positive and if the angle b/w ⊕ faces increases then shear strain is taken as negative.



⊖ Shear Strain

→ Alternatively shear strain associated with ⊕ Shear stress is positive and shear strain associated with ⊖ Shear stress is negative.

→ Strain is the fundamental quantity but stress is the derive constant.

→ Normal strain can be measured using extensometer or strain gauge. but stress can only be calculate.

① → Volume of specimen increases due to tension in region (A to D)

→ Deformation in region (D to D) is an account of normal stresses.

• DE:- Plastic Zone -

→ Region (D to E) we called plastic region, in these region without significant increases in stress these is called plastic flow.

→ Volume of the specimen does not change in region (D-E)

→ Shear is responsible for deformation.

* Distortion:- Volume change without deformation.

* E - Beginning of strength/strain hardening:-

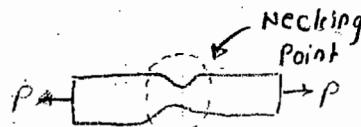
• E-F:- is called strain hardening region.

→ Beyond point (E) due to change in a crystalline structure of material, material starts offering resistance against deformation. This is called strain hardening.

* F - Ultimate stress - point:-

• F-G:- Region is called necking region

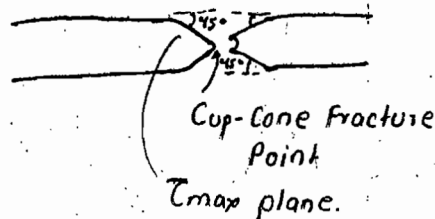
* G - Fracture point:-



→ In the necking region local instability section & cross-section of member at a particular point starts decreasing rapidly as other point. This is called necking.

→ In a strain control testing the applied force requirement decreases and hence strain-stress curve. false, ultimately fracture occurs at point G.

→ The fracture is a Cup-cone fracture.



→ Shear is responsible for fracture in mild steel, in fact / Percentage reduction in CS Area upto the time of fracture point is about 50%.