

LECTURE 01 – INTRODUCTION TO POWER ELECTRONICS

Victory belongs
to the most
persevering.
- Napoleon Bonaparte

POWER ELECTRONICS

GATE WEIGHTAGE 8-10 Marks

Books: MH Rashid, PS Bimbhra

Theory Problems

COURSE DURATION

80 TO 85 HOURS

Exam Year	1 Mark Question	2 Mark Question	Total Mark
2011	2	3	8
2012	2	3	8
2013	0	7	14
2014 Set-1	2	3	8
2014 Set-2	1	3	7
2014 Set-3	0	3	6
2015 Set-1	2	3	8
2015 Set-2	2	3	8
2016 Set-1	2	4	10
2016 Set-2	3	4	11
2017 Set-1	4	2	8
2017 Set-2	4	3	10
2018	3	3	9
2019	2	4	10
2020	4	2	8
2021	1	3	7
2022	3	4	11
2023	2	2	6
2024	3	4	11

Weightage of Power Electronics in Recent Years

CHAPTER	2024	2023	2022	2021	2020	2019	2018	AVERAGE
POWER SEMICONDUCTOR DEVICES	1	2	1	0	1	0	1	0.86
RECTIFIERS	2	2	6	1	3	5	4	3.29
DC-DC CONVERTERS	3	2	2	4	2	4	4	3
INVERTERS	2	0	2	2	1	1	0	1.14
AC VOLTAGE CONTROLLERS	1	0	0	0	1	0	0	0.29
DRIVES	2	0	0	0	0	0	0	0.29
TOTAL	11	6	11	7	8	10	9	8.86

Weightage of Power Electronics by IIT Roorkee

CHAPTER	2009	2017 Set 1	2017 Set 2
POWER SEMICONDUCTOR DEVICES	4	1	0
RECTIFIERS	2	2	5
DC-DC CONVERTERS	2	2	2
INVERTERS	2	2	3
AC VOLTAGE CONTROLLERS	0	0	0
DRIVES	0	0	0
TOTAL	10	7	10

Syllabus

POWER SEMICONDUCTOR DEVICES

- > SWITCHES
- > POWER DIODE
 - [BJT
 - MOSFET
 - IGBT
- > POWER TRANSISTOR
- > SCR
- > THYRISTOR

PHASE CONTROLLED CONVERTERS

- > 1 - Φ
 - [HALF WAVE
 - FULL WAVE
- > 3 - Φ
 - [HALF WAVE
 - FULL WAVE
- > Source Inductance
- > Dual converter (ESE)

CHOPPERS

- BUCK
- BOOST
- BUCK-BOOST
- THYRISTOR COMMUTATION

INVERTERS

- 1- Phase
 - 3- Phase
 - PWM
 - Resonance Converter
 - AC and DC Drive
 - SMPS
 - AC voltage controller
- ESE

Schedule

Power Electronic Switches

Date	Lecture Number	Lecture Title	Complete Title	Time
07-Oct-24	Lecture-01	Introduction to Power Electronics	Lecture-01: Introduction to Power Electronics	6:00 AM
07-Oct-24	Lecture-02	Power Semiconductor Switches Part-01	Lecture-02: Power Semiconductor Switches Part-01	8:00 AM
08-Oct-24	Lecture-03	Power Semiconductor Switches Part-02	Lecture-03: Power Semiconductor Switches Part-02	6:00 AM
08-Oct-24	Lecture-04	Power Diode Part-01	Lecture-04: Power Diode Part-01	8:00 AM
09-Oct-24	Lecture-05	Power Diode Part-02	Lecture-05: Power Diode Part-02	6:00 AM
09-Oct-24	Lecture-06	Assignment Discussion	Lecture-06: Assignment Discussion	8:00 AM
10-Oct-24	Lecture-07	Power Transistors Part-01	Lecture-07: Power Transistors Part-01	6:00 AM
10-Oct-24	Lecture-08	Power Transistors Part-02	Lecture-08: Power Transistors Part-02	8:00 AM
11-Oct-24	Lecture-09	Thyristors Part-01	Lecture-09: Thyristors Part-01	6:00 AM
11-Oct-24	Lecture-10	Thyristors Part-02	Lecture-10: Thyristors Part-02	8:00 AM
12-Oct-24	Lecture-11	Thyristors Part-03	Lecture-11: Thyristors Part-03	6:00 AM
12-Oct-24	Lecture-12	Assignment Discussion	Lecture-12: Assignment Discussion	8:00 AM
13-Oct-23				
14-Oct-23	Lecture-13	Thyristors Part-04	Lecture-13: Thyristors Part-04	6:00 AM
14-Oct-23	Lecture-14	Thyristors Part-05	Lecture-14: Thyristors Part-05	8:00 AM

Rectifiers

Date	Lecture Number	Lecture Title	Complete Title	Time
15-Oct-23	Lecture-15	Introduction to Phase Controlled Converters	Lecture-15: Introduction to Phase Controlled Converters	6:00 AM
15-Oct-23	Lecture-16	Single Phase Rectifier Part-01	Lecture-16: Single Phase Rectifier Part-01	8:00 AM
16-Oct-23	Lecture-17	Single Phase Rectifier Part-02	Lecture-17: Single Phase Rectifier Part-02	6:00 AM
16-Oct-23	Lecture-18	Assignment Discussion	Lecture-18: Assignment Discussion	8:00 AM
17-Oct-23	Lecture-19	Single Phase Rectifier Part-03	Lecture-19: Single Phase Rectifier Part-03	6:00 AM
17-Oct-23	Lecture-20	Single Phase Rectifier Part-04	Lecture-20: Single Phase Rectifier Part-04	8:00 AM
18-Oct-23	Lecture-21	Single Phase Rectifier Part-05	Lecture-21: Single Phase Rectifier Part-05	6:00 AM
18-Oct-23	Lecture-22	Single Phase Rectifier Part-06	Lecture-22: Single Phase Rectifier Part-06	8:00 AM
19-Oct-23	Lecture-23	Single Phase Rectifier Part-07	Lecture-23: Single Phase Rectifier Part-07	6:00 AM
19-Oct-23	Lecture-24	Three Phase Rectifiers Part-01	Lecture-24: Three Phase Rectifiers Part-01	8:00 AM
20-Oct-23				
21-Oct-23	Lecture-25	Assignment Discussion	Lecture-25: Assignment Discussion	6:00 AM
21-Oct-23	Lecture-26	Three Phase Rectifiers Part-02	Lecture-26: Three Phase Rectifiers Part-02	8:00 AM
22-Oct-23	Lecture-27	Three Phase Rectifiers Part-03		6:00 AM
22-Oct-23	Lecture-28	Three Phase Rectifiers Part-04	Lecture-28: Three Phase Rectifiers Part-04	8:00 AM
23-Oct-23	Lecture-29	Line Commutated Inverters and Source Inductance	Lecture-29: Line Commutated Inverters and Source Inductance	6:00 AM
23-Oct-23	Lecture-30	Assignment Discussion	Lecture-30: Assignment Discussion	8:00 AM

DC-DC Converters

Date	Lecture Number	Lecture Title	Complete Title	Time
24-Oct-23	Lecture-31	Step Down Choppers	Lecture-31: Step Down Choppers	6:00 AM
24-Oct-23	Lecture-32	Buck Converters	Lecture-32: Buck Converters	8:00 AM
25-Oct-23	Lecture-33	Boost and Buck Boost Converters	Lecture-33: Boost and Buck Boost Converters	6:00 AM
25-Oct-23	Lecture-34	Thyristor Commutation Part-01	Lecture-34: Thyristor Commutation Part-01	8:00 AM
26-Oct-23	Lecture-35	Assignment Discussion	Lecture-35: Assignment Discussion	6:00 AM
26-Oct-23	Lecture-36	Thyristor Commutation Part-02 & Types of Choppers	Lecture-36: Thyristor Commutation Part-02 & Types of Choppers	8:00 AM

Inverters

Date	Lecture Number	Lecture Title	Complete Title	Time
27-Oct-23	Lecture-37	Single Phase Inverters	Lecture-37: Single Phase Inverters	6:00 AM
27-Oct-23	Lecture-38	Single Phase Inverters and Current Source Inverters	Lecture-38: Single Phase Inverters and Current Source Inverters	8:00 AM
28-Oct-23	Lecture-39	Three Phase Inverters	Lecture-39: Three Phase Inverters	6:00 AM
28-Oct-23	Lecture-40	Assignment Discussion	Lecture-40: Assignment Discussion	8:00 AM
29-Oct-23	Lecture-41	Pulse Width Modulation	Lecture-41: Pulse Width Modulation	6:00 AM

Miscellaneous

Date	Lecture Number	Lecture Title	Complete Title	Time
29-Oct-23	Lecture-42	AC Voltage Regulators	Lecture-42: AC Voltage Regulators	8:00 AM
30-Oct-23	Lecture-43	Dual Converters & Cycloconverters	Lecture-43: Dual Converters & Cycloconverters	6:00 AM
30-Oct-23	Lecture-44	AC & DC Drives Part-01	Lecture-44: AC & DC Drives Part-01	8:00 AM
31-Oct-23	Lecture-45	AC & DC Drives Part-02	Lecture-45: AC & DC Drives Part-02	6:00 AM
31-Oct-23	Lecture-46	Resonant Converters and SMPS	Lecture-46: Resonant Converters and SMPS	8:00 AM
03-Nov-23	Lecture-47	Assignment Discussion	Lecture-47: Assignment Discussion	6:00 AM

Strategy

→ *Fourier Series*

1. No Pre-requisite (Basic of semi conductor)
2. No need of standard books
3. No need to make complete notes
4. Make hand written short notes

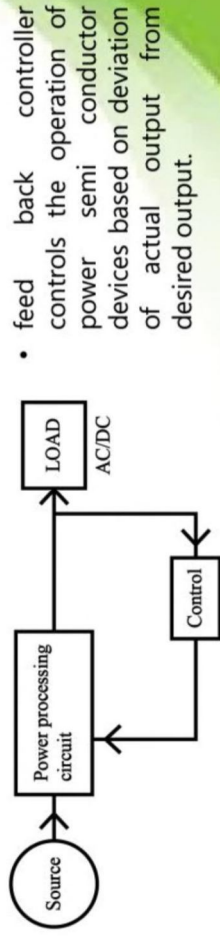
→ Attend live classes daily → Attempt weekly Quiz
 → Make short notes → Solve PYQs
 → Resolve class questions (*weekend*)
 → Practice DPP

1. DPP

2. Structured Notes
3. Weekly Quiz
4. Doubts
5. Shorts notes

Basics of Power Electronics

- Power electronics is a technology associated with efficient conversion & control of electrical power semiconductor devices. Power processing circuit converts into different platform from similar platform.
- This acts as an interfacing circuit & it is also used to regulate or control of output. It contain power semiconductor devices.



- feed back controller controls the operation of power semiconductor devices based on deviation of actual output from desired output.

Basics of Power Electronics

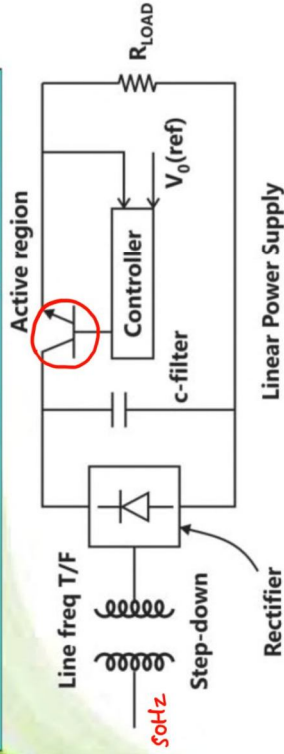
- Feedback controller compares the output of power processing ckt with a desired reference & error between 2 values is minimized.
- Error is minimized by controlling the switching of power semiconductor devices.
- Firing circuits: Circuits that are used to trigger a power semiconductor device.

Power Electronics Vs Analog Electronics

- In power conversion process, low energy loss and high η is desirable because
 - i. Cost of wasted energy
 - ii. Difficult to remove heat generated due to wasted energy
- Other important aspect is reduction in size, weight and cost
- These objective cannot to met by linear ICs where active device operates in linear region and line frequency. T/F is used for isolation.

→ 50Hz

Power Electronics Vs Analog Electronics



➤ In power electronics, device is made to operate as a switch at high switching frequency (300 kHz–1MHz) & high frequency T/F is used for isolation & hence size & weight of T/F reduces

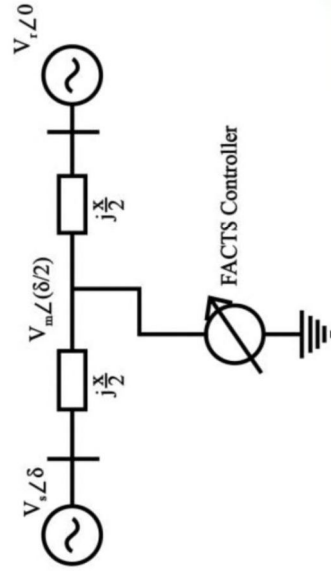
Such a supply is called switch mode power supply (SMPS)

Application of Power Electronics

1. Switch mode power supply and uninterrupted power supply.
2. Energy conversion: in a conventional pump, motor rotates at constant speed o/p of pump is controlled by **value** & constant power is drawn from supply.
 $\text{Uart} \rightarrow \text{ac} \rightarrow \text{dc}$
3. If pump is controlled by **variable speed drive** then power i/p can be controlled
3. Process control & factory automation
4. Transportation: EVs use battery chargers & PE
5. Welding, electroplating & induction heating
6. HVDC (rectifier at sending end & inverter at receiving end)
7. Home automation

Power Systems

➤ By use of FACTS controller we can perform reactive power compensation which can help control voltage & improve stability.



Transportation

- Electric Vehicle $\rightarrow$ dc motor
- $\rightarrow$ Battery chargers (ac $\rightarrow$ dc)
- $\rightarrow$ Motor Control [Chopper Controlled DC motor]
 - $\rightarrow$ controls the dc voltage based on duty cycle of switch
- Electric locomotives
- Speed control dc motor $\rightarrow$ Armature voltage control (control V_t)
 - field control (control I_f)
 - above N_{base}
 - below N_{base}

Low Power Application

- Trimmers: Battery + dc motor
 - Battery charge: ac → dc converter
 - Speed control of dc motor
- Laptop & mobile chargers (ac → dc)
- Fan Speed control (triac : ac → ac)

Renewable Energy Source (Medium Power Applications)

- Solar power converter
 - Solar cells produce dc power
 - dc power must be converted to ac power before connecting to grid
 - Inverters are required for dc → ac conversion

Advantages

1. Power electronic circuits don't have any rotational parts, so that all losses in system will reduce. (no friction & windage losses).
2. When the losses are less, heat dissipation is also less, therefore it requires less cooling efforts.
3. Power electronics equipment are compact in size.
4. The closed loop control is possible with power electronic circuits.
5. High reliability & less maintenance.
6. Long life due to absence of moving parts.

Disadvantages

1. Harmonics is major drawback of power electronics system.
2. Non-linear loads are the source of harmonics.
3. Harmonics is defined for non-sinusoidal periodic signals. In power electronics due to switching harmonics are generated.
4. The power semi-conductor devices will operate as switches, due to this switching action, all waveforms are non-sinusoidal & periodic in nature and such function can be expressed in terms of Fourier series

Question

Why harmonics are undesirable?

→ waveform becomes non-sinusoidal

→ Degrade quality of electric power supply. $I_{rms} = [I_1^2 + I_2^2 + I_3^2 \dots]^{1/2}$

→ Increased losses in distribution system. $(I_{rms})^2 R t$

→ Overload in neutral conductor → neutral carries zero sequence or triplex harmonic current **for balanced system $I_n = 0$**

→ Vibrations & premature ageing of generator, motor, T/F

→ Increase in noise level

→ Distortion in supply can disturb operation of sensitive load.

→ Disturbance in telephone or comm. line (zero sequence)

→ Increase in m/c core losses. ($P_{h \propto f$, $P_e \propto f^2$) **→ triplex harmonics**

Fourier Series (Trigonometric)

*** CN

(a) for an even function

→ wave form symmetric about vertical axis

$$x(-t) = x(t) \\ b_n = 0$$

(b) for an odd function

→ waveform is symmetric about origin (1st & 3rd quad / 2nd & 4th quad)

$$x(-t) = -x(t) \\ a_0 = a_n = 0$$

(c) half wave symmetry

$$x(t + T/2) = -x(t)$$

only odd harmonics exist $a_n, b_n = 0 \forall n = \text{even}$

Fourier Series (Trigonometric)

➤ Any periodic function can be expressed as a linear combination of harmonically related sinusoids

(Frequency are a multiple of a fundamental frequency)

$$x(t) = a_0 + \sum_{n=1}^{\infty} [a_n \cos n\omega_0 t + b_n \sin n\omega_0 t] \quad \omega = n\omega_0, \omega_0 = \text{fund. Freq.}$$

a_0 = average value or dc component = $1/T \int_{(T)} x(t) dt$

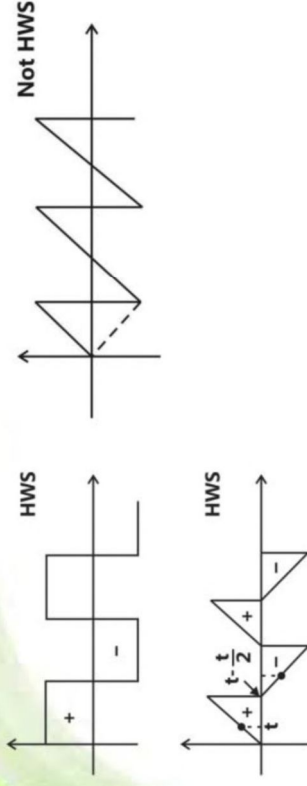
$$a_n = \frac{2}{T} \int_{(T)} x(t) \cos n\omega_0 t dt$$

<T>: **integral over one period**
0 → T

$$b_n = \frac{2}{T} \int_{(T)} x(t) \sin n\omega_0 t dt$$

-T/2 → T/2
-T/4 → 3T/4
etc

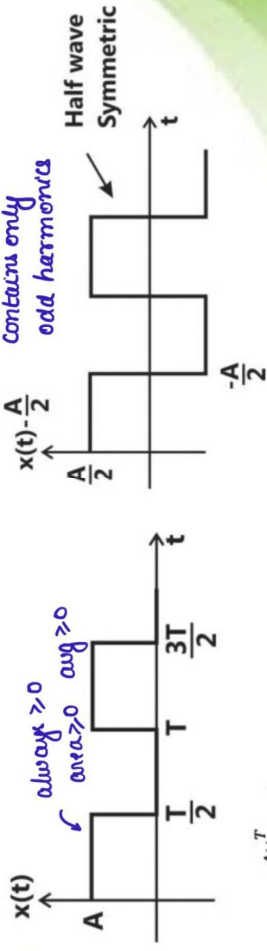
Fourier Series (Trigonometric)



➤ -ve half cycle should be mirror image of +ve half cycle about time axis.

Hidden Symmetry

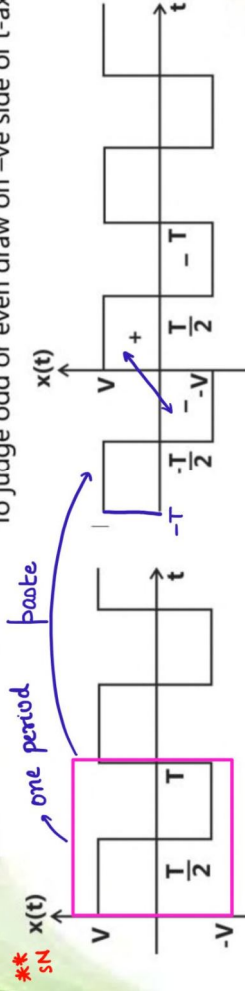
- > For functions having non-zero average value, subtract average value from functions i.e shift graph downwards by an amount equal to average & then check for HWS



$$avg = \frac{A \times \frac{T}{2}}{T} = \frac{A}{2}$$

Important Waveforms

To judge odd or even draw on -ve side of t-axis



$$b_n = \frac{2}{T} \int_0^T x(t) \sin n\omega t dt$$

$< T$

$$b_n = 0 \quad \forall n = \text{even}$$

$$a_0 = a_n = 0$$

Odd function & half wave symmetric

Side effect of harmonics

1. Due to high frequency components in form of harmonics core losses in Induction Motor will increase and can damage the motor.
2. Input power factor of full control rectifier & AC voltage regulator is low due to harmonics.

$$b_n = \frac{2}{T} \left[\int_0^{T/2} V \sin n\omega t dt + \int_{T/2}^T (-V) \sin n\omega t dt \right]$$

$$= \frac{2V}{T} \left[\left(-\frac{\cos n\omega t}{n\omega} \right) \Big|_0^{T/2} - \left(-\frac{\cos n\omega t}{n\omega} \right) \Big|_{T/2}^T \right]$$

$$= \frac{2V}{n\omega T} \left[1 - \cos n\omega T/2 + \cos n\omega T - \cos n\omega T/2 \right]$$

$$\omega_0 T = 2\pi \quad \omega_0 T = 2\pi$$

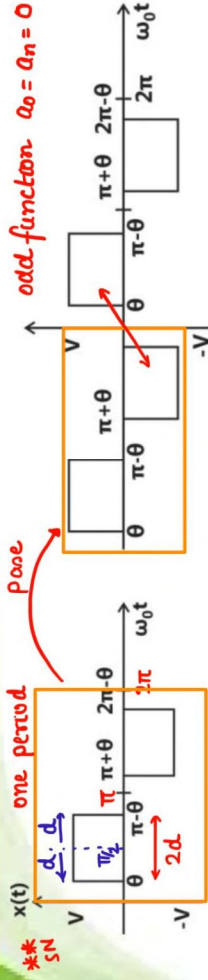
$$b_n = \frac{2V}{2n\pi} \left[1 - \cos n\pi + \cos 2n\pi - \cos n\pi \right]$$

$$= \frac{2V}{n\pi} (1 - \cos n\pi) = \begin{cases} \frac{4V}{n\pi} & n = \text{odd} \\ 0 & n = \text{even} \end{cases}$$

$$x(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \sin n\omega t$$

Important Waveforms

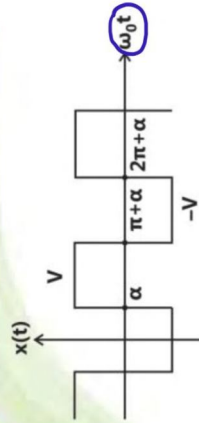
Quasi-Square wave



half wave symmetric
 $b_n = 0 \forall n = \text{even}$

$$b_n = \frac{2}{2\pi} \int_0^{2\pi} x(t) \sin n\omega_0 t d(\omega_0 t) - \int_{\pi-\theta}^{\pi+\theta} V \sin n\omega_0 t d(\omega_0 t)$$

Important Waveforms



$x(t - t_0)$: right shift
 $x(t + t_0)$: left shift

$$x(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \sin(n(\omega_0 t - \alpha))$$

$$= \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \sin(n\omega_0 t - n\alpha)$$

$$b_n = \frac{V}{\pi} \left[\left(-\frac{\cos n\omega_0 t}{n} \right)^{\pi-\theta} - \left(-\frac{\cos n\omega_0 t}{n} \right)^{\pi+\theta} \right]$$

$$= \frac{V}{n\pi} \left[\cos n\theta - \cos(n\pi - n\theta) + \cos(2n\pi - n\theta) - \cos(n\pi + n\theta) \right]$$

$$= \frac{V}{n\pi} \left[2\cos n\theta - 2\cos(n\pi - n\theta) \right]$$

$$= \frac{2V}{n\pi} (\cos n\theta - \cos(n\pi - n\theta))$$

$= 0$ $n = \text{even}$

$= \frac{4V}{n\pi} \cos n\theta$ $n = \text{odd}$

SN

$$x(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \cos n\theta \sin n\omega_0 t$$

$$x(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \sin n\pi/2 \sin n\omega_0 t$$

$$\cos n\theta = \cos(n\pi/2 - n\theta)$$

$$= \cos n\pi/2 \cos n\theta + \sin n\pi/2 \sin n\theta$$

$L_3 = 0$ $n = \text{odd}$

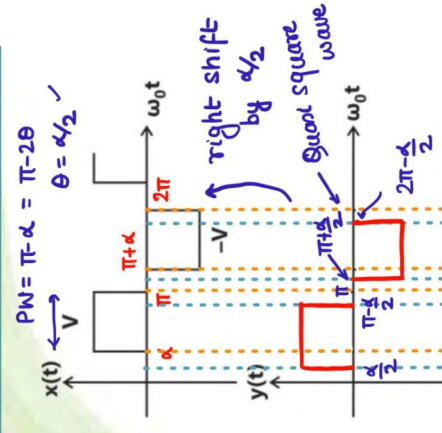
SN

$$2d = \text{pulse width}$$

$$2d = (\pi - \theta) - \theta = \pi - 2\theta$$

$$d = \pi/2 - \theta \quad \theta = \pi/2 - d$$

Important Waveforms



$$y(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \cos n\frac{\alpha}{2} \sin n\omega_0 t$$

$$x(t) = \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \cos n\frac{\alpha}{2} \sin(n(\omega_0 t - \frac{\alpha}{2}))$$

$$= \sum_{n=1,3,5}^{\infty} \frac{4V}{n\pi} \cos n\frac{\alpha}{2} \sin(n\omega_0 t - n\frac{\alpha}{2})$$